RE-E 92003/2023-10-30 Replaces: 2021-08-11



# Axial piston variable pump A4VG series 32

# Europe



- ▶ High-pressure pump for applications in closed circuits
- ▶ Size 28 to 125
- Nominal pressure 400 bar
- ▶ Maximum pressure 450 bar

#### **Features**

- ▶ Integrated auxiliary pump for boost and pilot oil supply
- ► Flow direction changes when the swashplate is moved through the neutral position
- ► High-pressure relief valves with integrated boost function
- ▶ With adjustable pressure cut-off as standard
- ► Boost-pressure relief valve
- ► Through drive for mounting of further pumps up to same size
- ► Large variety of controls
- Swashplate design

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# Type code

01	02	03	04	05	06	07	08	09		10	11		12	2	13	14	15	16	17	18	19	20	21	22
A4V	G								/	32		_	N											
Axial	pistor	unit																						
01	Swasl	hplate	desig	n, vari	iable,	nomin	al pre	ssure	400 b	ar, ma	ximur	n pre	ssure	e 45	50 ba	ır								A4V
Opera	iting n	node																						
02	Pump	, clos	ed circ	cuit																				G
Size (	NG)																							
03	Geom	etric	displa	cemen	ıt, see	"Tech	nical o	data" c	n pag	ge 10								28	40	56	71	90	125	
Contr	ol dev	vice																28	40	56	71	90	125	
- 1		rtiona		•				d, wit	h inle	t filtra	tion ir	<b>P</b> <sup>1)</sup>						•	•	•	•	•	•	HD:
	contro	ol hyd	raulic	m	echan	ical se	rvo											•	•	•	•	•	•	HW
	Auton	natic c	ontro	l, spee	ed rela	ited									U	= 12 \	/	•	•	•	•	•	•	DA
															U	= 24 \	/	•	•	•	•	•	•	DA:
				-											***	10.1	,	•	•	•	•	•	•	DG
						•			d						_	= 12 \		•	•	•	•		_	EP:
																= 12 \		•	•	•	•			EZ
	electr		.0111101	., •••	itii Svvi	itemine	30ter	ioid							-	= 24 \		•	•	•	•	90 125 90 125 90 125 0 0 H 0 0 E 0 0		EZ
_	Electr	onic o	hydraulic mechanical servo  tic control, speed related  tic control, direct operated  tional with proportional solenoid electric with inlet filtration in P1)  int control, with switching solenoid  nic control direct operated by two pressure reducing valves; prepared for BODAS software2)  direct operated by two pressure reducing valves (FTDRE  direct operated by two pressure reducing valves (DRE5)								= 12 \		•	•	-	-	1		ETA					
											Ü				$\overline{U}$	= 24 \	/	•	•	-	-	-	•	ETE
				di	rect o	perate	d by t	wo pre	essure	redu	cing v	alves	(FTD	RE	) <i>U</i>	= 12 \	/	•	•	-	-	-	90 125 90 125 90 125 0	ET
															U	= 24 \	/	•	•	_	-	_	_	ET4
				di	rect o	perate	d by t	wo pre	essure	redu	cing v	alves	(DRE	<b>E</b> 5)	U	= 12 \	/		-	-	-	-	•	ET7
															U	= 24 \	/		_		-	_	•	ET8
ress	ure cu	t-off																28	40	56	71	90	125	
05	Witho	ut pre	essure	cut-of	ff (wit	hout c	ode) <sup>3</sup>											•	•	-	-	-	•	
	Press	ure cu	t-off															•	•	•	•	•	•	D
leutr	al pos	ition	switch	1														28	40	56	71	90	125	
H								code)										•	•	•	•	•	•	
	Neutr	al pos	ition	witch	(only	for H\	N con	trol)										•	•	•	•	•	•	L
/lecha	anical	strok	e limi	ter														28	40	56	71	90	125	
								ut cod										•	•	•	•	•	•	
	Mech	anical	strok	e limit	er, ext	ernall	y adju	stable										•	•	•	•	•	•	М
1		ambe																28	40	56	71	90	125	
08	Witho	ut str						<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub>	(with	out co	de)							•	•	•	•	•	•	
- F			amber															•		•				Т

<sup>1)</sup> Sizes 28 to 71 are designed with inlet filtration in  ${\bf P}$  and  ${\bf X}_1/{\bf X}_2$ 

<sup>2)</sup> The ETA/ETB control is only permissible in combination with port plate 22 or 30, see position 15 "Port thread: Metric with O-ring seal following ISO 6149".

 $_{\mbox{\scriptsize 3)}}$  Version not available for all port plate variants, please contact us.

<b>14V</b>	/ G								7	32		<u> </u>	N	Т	$\top$									
	-									02			'											
	ontrol																HD	HW	DG	DA	EP	EZ	ET	_
09			contr														•	•	•	_	•	•	•	1
					setting												•	•	•	•	•	-	-	2
			valve, on leve		anicall	y adju	stable						ckwi	se			•	•	•	•	•	-	-	3F
	VVICII	positio	JII LEVE	<b>2</b> 1						of ac clockw		n,					•	•	•	•	•	-	-	31
	DA co	ntrol	valva	fived	setting	nort	s for r										•	•	<del> </del>	•	•	_	<del> </del> _	7
					setting												+	+			<u> </u>			<del>'</del>
	1				luid, n	-	-		ii vac	ve illo	arrica,	'					-	-	-	•	-	-	-	8
erie	s																							
10	Serie	s 3, in	dex 2																					32
irec	tion o	f rota	tion															28	40	56	71	90	125	
11	Viewe	ed on	drive s	haft									C	clockv	vise			•	•	•	•	•	•	R
													-	count	er-clo	ckw	/ise	•	•	•	•	•	•	L
eali	ng ma	terial																28	40	56	71	90	125	
12			rubb	er), sh	naft se	al mad	de of F	KM (f	luoro	carbor	rubb	er)						•	•	•	•	•	•	N
rive	shaft																	28	40	56	71	90	125	
13		ed sha	aft			fo	or sing	le pun	gn									•	•	•	•	•	•	Z
	DIN 5					_		_ <u>·</u> _	•	mp –	1st pu	ımp						_4)	•	•	•	•	•	Δ
	Splin	ed sha	aft			fc	or sing	le pun	np									•	•	•	•	•	•	5
	ANSI	B92.1	a			_		_		mp –	1st pu	ımp		-				_5)	_5)	•	•	_5)	•	T
						_				n pun			ımp					<b> </b> -	•	-	-	•	-	U
lour	nting f	lange																28	40	56	71	90	125	
14	SAE									2	-hole							•	•	•	_	_	_	С
										4	-hole							<b> </b> -	-	-	-	-	<b> </b>	D
										_	+4-ho	le						<b> </b>	<u> </u>	-	•	•	•	F
lork	ing po	ort (no	rt nla	to)															1					_
15					h prof	ile sea	aling r	ing se	al bas	ed on	DIN 3	3852						7						
					SAE								ccor	ding	to DI	N 13	3	28	40	56	71	90	125	
	SAE	workin	g port	<b>A</b> and	<b>B</b> , to	p and	botto	m		S	uctior	port	<b>S</b> bo	ottom				-	•	•	•	•	•	02
	SAE	workin	g port	<b>A</b> and	<b>B</b> , to	p and	botto	m		S	uctior	port	<b>S</b> at	top				-	•	•	0	0	0	0:
	SAE v	workin	g port	<b>A</b> and	<b>B</b> , sa	ıme si	de righ	nt <sup>6)</sup>		S	uctior	port	<b>S</b> bo	ottom				•	-	-	-	-	-	4
	SAE	workin	g port	<b>A</b> and	d <b>B</b> , sa	ıme si	de left	6)		s	uctior	port	<b>S</b> bo	ottom				-	-	-	•	0	•	10
	SAE	workin	g port	<b>A</b> and	<b>B</b> , sa	ıme si	de righ	nt <sup>6)</sup>		S	uctior	port	<b>S</b> at	top				_	_	-	0	0	0	1.
	SAE	workin	g port	<b>A</b> and	d <b>B</b> , sa	ıme si	de left	6)		s	uctior	port	<b>S</b> at	top				•	_	•	-	-	_	13
	1				h O-ri	-																		
					SAE				throu							N 13	3	28	40	56	71	90	125	
					d <b>B</b> , to						uction							<del>  -</del>	•	-	-	-	•	2:
	I SAE v	workin	g port	A and	d <b>B</b> . sa	ıme si	de righ	۱t <sup>٥)</sup>		S	uctior	nort	S bo	ottom				•	_	-	I -	I -	-	30

<sup>4)</sup> Standard for combination pump – 1st pump: Shaft Z

<sup>5)</sup> Standard for combination pump – 1st pump: Shaft S

<sup>6)</sup> Only possible without attachment filter

# 4 **A4VG series 32** | Axial piston variable pump Type code

01	02	03	04	05	06	07	. 08	09		10	. 11		12	13	14	15	<u>. 16</u>	17	18	19	20	21	22
A4V	G								/	32		_	N										
Boos	t pumi	р															28	40	56	71	90	125	
16	<del></del>	•	egrate	d boo	st pum	np				v	vithou	t throu	ıgh dr	ive			•	•	•	•	•	•	N
										v	vith th	rough	drive				•	•	•	•	•	•	K
	Integ	rated	boost	pump						V	vith ar	nd with	nout t	hrou	gh driv	e	•	•	•	•	•	•	F
Γhro	ugh dri	ive <sup>7)</sup>															28	40	56	71	90	125	
17	Witho	out thi	rough	drive,	only fo	or vers	sion N	and F	(pos	ition 1	6)						•	•	•	•	•	•	00
	Flang	ge SAE	J744	Н	ub for	spline	ed sha	ft															
	82-2	(A)		5/	8 in	9	T 16/3	32DP <sup>8</sup>	)								•	•	•	•	•	•	01
				3/	4 in	1	1T 16	/32DF	8)								-	•	•	•	-	-	52
	101-2	2 (B)		7/	8 in	1	3T 16,	/32DF	8)								•	•	•	•	•	•	02
				1	in	1	5T 16,	/32DF	8)								•	•	•	•	•	•	04
	127-2	2 (C)		1	in	1	5T 16,	/32DF	8)								_	•	-	-	-	-	09
	127-2	2 (C)		1	1/4 in	1	4T 12	/24DF	8)								_	_	•	•	_		07
	127-2	2/4 (C	)														-	-	-	-	•	•	07
	152-2	2/4 (D	)	W	35	2	×30×1	6×9g <sup>9</sup>	)									_	-	-	•	-	73
				1	3/4 in	1	3T 8/	16DP <sup>8</sup>	)									_	_	_	_	•	69
ligh-	nrocci																						
	hiesar	ure re	lief va	lve						Setti	ng ran	ge $\Delta p_{\scriptscriptstyleert}$	ID				28	40	56	71	90	125	
18	<del></del>				ve, pilo	ot ope	erated				ng ran 420			th by	pass		28	40	56 -	71	90	125	1
18	High-	pressi		ief val		ot ope	erated			100		) bar	wi		pass t bypas	SS		T					1
18	High-	pressi pressi	ure rel	ief val	ve	ot ope	erated			100	420	) bar	wi	thou		SS	-	-	-	•	•	•	
18	High-	pressi pressi	ure rel ure rel	ief val	ve	ot ope	erated			100 250	420	) bar ) bar	wi wi	thout	t bypas		-	-	-	•	•	-	3
18	High-	pressi pressi	ure rel ure rel	ief val	ve	ot ope	erated			100 250	420	) bar ) bar	wi wi wi	thout th by	t bypas pass		-	-	-			-	3
	High-	pressi pressi t oper	ure rel ure rel ated, f	ief val ief val ïxed s	ve etting			re sup	ply	100 250	420	) bar ) bar	wi wi wi	thout th by	t bypas pass t bypas		•	-	-				3 5 4
iltra	High- High- direct	pressi pressi t oper	ure rel ure rel ated, f	ief val ief val iixed s	ve etting	ost p	ressui	re sup	ply	100 250	420	) bar ) bar	wi wi wi	thout th by	t bypas pass t bypas		•	-	-		• - - -	- - -	3 5 4
iltra	High- direct	pressi pressi t oper	ure relure related, f	ief val ief val iixed s iixed s	ve etting rnal bo	oost p	<b>ressu</b> n line		ply	100 250	420	) bar ) bar	wi wi wi	thout th by	t bypas pass t bypas		- • • • • • • • • • • • • • • • • • • •	- • • • • • • • • • • • • • • • • • • •	- • • • • 56	• 71	• 90	• 125	3 5 4 6
iltra	High- direct	pressi pressi t oper	ure relure related, for the both the bo	ief vali ief vali ief vali ixed s ixed s	ve etting mal bo	ost p	<b>ressui</b> n line ure lin	e		100 250	420	) bar ) bar	wi wi wi	thout th by	t bypas pass t bypas		- • • •	- • • • • 40	- • • •	• 71	• 90	• 125	3 5 4 6
iltra	High- High- direct	pressi pressi t oper	ure relure related, for the bound the boundary of the boundary	/exter	ve etting  nal bo  nump s	oost p suctio pressu	ressui n line ure line ation	e		100 250	420	) bar ) bar	wi wi wi	thout th by	t bypas pass t bypas		- • • • • • • • • • • • • • • • • • • •	- • • • • • • • • • • • • • • • • • • •	- • • • • 56	• 71	• 90	• 125	3 5 4 6
iltra	High- High- direct	pressi pressi t oper coost of tion in tion in achme	ure relure related, for the boxternal ent filteent filte	ief valief valie	rnal bo bump s bump p t circuin cold	oost p suctio pressu it filtr start start	ressui n line ure line ation valve valve	e ( <b>F</b> <sub>e</sub> an	d <b>F</b> <sub>a</sub> ) sual c	100 250 100 ontam	420 420	) bar ) bar ) bar	wi wi wi wi wi	thout th by thout th by	t bypas pass t bypas		28	40	- • • • • 56	• 71 • •	90	• 125 • •	3 5 4 6 S
iltra	High- High- direct	pressi pressi t oper tion in tion in tion in achme	ure relure related, for the boxternal ent filteent filte	/exter coost p	nal bo	oost p suctio pressu it filtr start start	ressui n line ure line ation valve valve	e ( <b>F</b> <sub>e</sub> an	d <b>F</b> <sub>a</sub> ) sual c	100 250 100 ontam	420 420	) bar ) bar ) bar	wi wi wi wi wi	thout th by thout th by	t bypas pass t bypas		28	40	- • • • 56	• 71 • • • •	90	• 125 • • • •	3 5 4 6 S D F
	High- High- direct	pressi pressi t oper tion in tion in achme achme	ure relure related, for the batternal ent filtent filten norma	/exter coost p	nal bo	post p suctio pressu it filtr start start start	ressui n line ure line ation valve valve a	e ( <b>F</b> <sub>e</sub> an	d <b>F</b> <sub>a</sub> ) sual c	100 250 100 ontam	420 420 250	o bar  bar  bar  in indic	wi wi wi wi wi	tthouthouth by	t bypas rpass t bypas rpass		28	40	- • • • • • • • • • • • • • •	• 71 • • • • •	90	•	3 5 4 6 S D F P
iltra 19	High- High- direct	pressi pressi t oper tion in tion in achme achme achme achme	ure rel ure rel ated, f circuit n the b external ent filt ent filt norma	/exter coost p	nal booump soump st circuin cold n cold en	post p suctio pressu it filtr start start start	ressui n line ure line ation valve valve a	e ( <b>F</b> <sub>e</sub> an	d <b>F</b> <sub>a</sub> ) sual c	100 250 100 ontam	420 420 250	o bar  bar  bar  in indic	wi wi wi wi wi	tthouthouth by	t bypas rpass t bypas rpass		28	40	56		90	125 • • • • •	3 5 4 6 S D F P B
iltra 19	High- High- direct	pressi pressi t oper tion in tion in achme achme achme achme achme	circuit, n the be external ent filte ent filte norma post pr	/exter coost p	nal booump soump st circuin cold n cold en	post p suction pressuit filtr start start start	ressui n line ure line ation valve valve a valve a	e ( <b>F</b> <sub>e</sub> an and vi and el	d <b>F</b> <sub>a</sub> ) sual c	100 250 100 ontam	420 420 250	o bar  bar  bar  in indic	wi wi wi wi wi	tthouthouth by	t bypas rpass t bypas rpass		28	40	- • • • • • • • • • • • • • • • • • • •	71 • • • • • • •	90 • • • • •	•	3 5 4 6 S D F P B

= Preferred program

o = On request - = Not available

= Available

<sup>7)</sup> Specifications for version with integrated boost pump, please contact us for version without boost pump

<sup>8)</sup> Hub for splined shaft according to ANSI B92.1a (Splined shaft in accordance with SAE J744)

<sup>9)</sup> Hub for splined shaft according to DIN 5480

<sup>10)</sup> The swivel angle sensor is used to detect the swivel angle and thus the displacement. For available options regarding the swivel angle detection, please contact us.

01	02	03	04	05	06	07	80	09		10	11		12	13	14	15	16	17	18	19	20	21	22
A4V	G								/	32		_	N										
Conn	ector	for so	lenoic	ls <sup>11)</sup>													28	40	56	71	90	125	
21	Witho	out co	nnecto	or (wit	hout	code),	only v	vith p	urely	hydrau	lic co	ntrols					•	•	•	•	•	•	
	DEUT	SCH	connec	ctor				wit	hout	suppr	essor	diode					•	•	•	•	•	•	Р
	mold	ed, 2- <sub>l</sub>	oin					wit	h sup	press	or dio	de (or	ly for	EZ an	d DA)		•	•	•	•	•	•	Q
Stand	lard/s	pecial	versi	on														•		,			
22	Stand	dard ve	ersion							with	out co	de											

22	Standard version	without code	
	Special version		-S

• = Available

o = On request

- = Not available

= Preferred program

#### **Notice**

- ▶ Note the project planning notes on page 92!
- ► In addition to the type code, please specify the relevant technical data when placing your order.
- ▶ Please note that not all type code combinations are available although the individual functions are marked as being available.

<sup>11)</sup> Connector specifications refers to control device, connectors for other electric components may deviate

# **Hydraulic fluids**

The axial piston unit is designed for operation with HLP mineral oil according to DIN 51524.

Application instructions and requirements for hydraulic fluid selection, behavior during operation as well as disposal and environmental protection should be taken from the following data sheets before the start of project planning:

- ▶ 90220: Hydraulic fluids based on mineral oils and related hydrocarbons
- ▶ 90221: Environmentally acceptable hydraulic fluids
- ▶ 90222: Fire-resistant, water-free hydraulic fluids (HFDR/HFDU)
- ▶ 90225: Limited technical data for operation with water-free and water-containing fire-resistant hydraulic fluids (HFDR, HFDU, HFAE, HFAS, HFB, HFC).

#### Selection of hydraulic fluid

Bosch Rexroth evaluates hydraulic fluids on the basis of the Fluid Rating according to the technical data sheet 90235.

Hydraulic fluids with positive evaluation in the Fluid Rating are provided in the following technical data sheet:

▶ 90245: Bosch Rexroth Fluid Rating List for Rexroth hydraulic components (pumps and motors)

Selection of hydraulic fluid shall make sure that the operating viscosity in the operating temperature range is within the optimum range ( $v_{opt}$ ; see selection diagram).

#### Viscosity and temperature of hydraulic fluids

	Viscosity	Shaft seal	Temperature <sup>3)</sup>	Remarks
Cold start	$v_{\text{max}} \le 1600 \text{ mm}^2/\text{s}$	NBR <sup>2)</sup>	ϑ <sub>St</sub> ≥ -40 °C	$t \le 3$ min, without load ( $p \le 50$ bar), $n \le 1000$ rpm
		FKM	ϑ <sub>St</sub> ≥ -25 °C	Permissible temperature difference between axial piston unit and hydraulic fluid in the system maximum 25 K
Warm-up phase	$v = 1600 \dots 400 \text{ mm}^2/\text{s}$			$t \le 15 \text{min}, p \le 0.7 \times p_{\text{nom}} \text{ and } n \le 0.5 \times n_{\text{nom}}$
Permissible	$v = 400 \dots 10 \text{ mm}^2/\text{s}^{1)}$	NBR <sup>2)</sup>	θ ≤ +85 °C	Measured at port T
operating range		FKM	θ ≤ +110 °C	
	$v_{\rm opt}$ = 36 16 mm <sup>2</sup> /s			Optimal operating viscosity and efficiency range
Short-term	$v_{min} = 10 7 \text{ mm}^2/\text{s}$	NBR <sup>2)</sup>	θ ≤ +85 °C	$t \le 3 \text{ min, } p \le 0.3 \times p_{\text{nom}}$ , measured at port <b>T</b>
operation		FKM	9 < +110 °C	

#### **Notice**

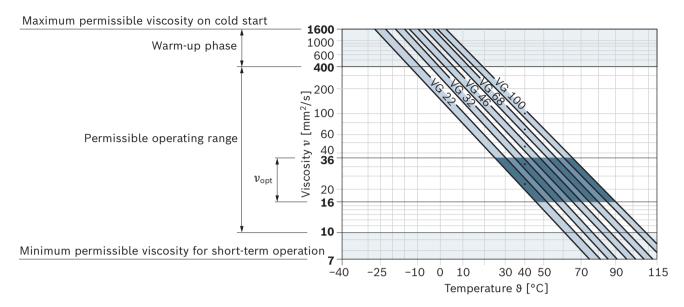
The maximum circuit temperature of +115 °C must not be exceeded at the working ports **A** and **B** complying with the permissible viscosity.

<sup>1)</sup> This corresponds, for example on the VG 46, to a temperature range of +4 °C to +85 °C (see selection diagram)

<sup>2)</sup> Special version, please contact us

<sup>3)</sup> If the temperature at extreme operating parameters cannot be adhered to, please contact us.

#### ▼ Selection diagram



# Filtration of the hydraulic fluid

Finer filtration improves the cleanliness level of the hydraulic fluid, which increases the service life of the axial piston unit.

A cleanliness level of at least 20/18/15 is to be maintained according to ISO 4406.

At a hydraulic fluid viscosity of less than 10 mm<sup>2</sup>/s (e.g. due to high temperatures during short-term operation), a cleanliness level of at least 19/17/14 according to ISO 4406 is required.

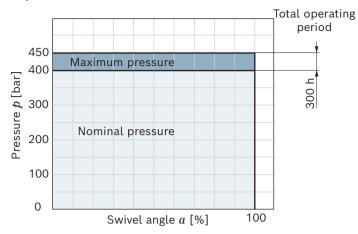
For example, a viscosity of 10 mm<sup>2</sup>/s corresponds to the following temperatures with the following media:

- ► HLP 32 a temperature of 73 °C
- ▶ HLP 46 a temperature of 85 °C

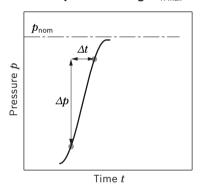
# **Working pressure range**

Pressure at working port A or B		Definition
Nominal pressure $p_{nom}$	400 bar	The nominal pressure corresponds to the maximum design pressure.
Maximum pressure $p_{\sf max}$	450 bar	The maximum pressure corresponds to the maximum working pressure within
Maximum single operating period	10 s	a single operating period. The sum of single operating periods must not ex-
Total operating period	300 h	ceed the total operating period.
Minimum pressure (low-pressure side)	10 bar above	Minimum pressure on the low-pressure side (A or B) required to prevent
	case pressure	damage to the axial piston unit.
		Boost pressure setting must be higher depending on system.
Rate of pressure change $R_{\rm A\ max}$	9000 bar/s	Maximum permissible speed of pressure build-up and reduction during
		a pressure change across the entire pressure range.
Boost pump		
Nominal pressure $p_{Sp\ nom}$	25 bar	
Maximum pressure $p_{\text{Sp max}}$	40 bar	
Pressure at suction port <b>S</b> (inlet)		
Continuous $p_{Smin}$	≥0.8 bar absolute	$v \le 30 \text{ mm}^2/\text{s}$
Short-term, at a cold start	≥0.5 bar absolute	<i>t</i> < 3 min
Maximum pressure $p_{S\;max}$	≤5 bar absolute	
Control pressure		
Minimum control pressure $p_{St\;min}$		Required control pressure $p_{\mathrm{St}}$ , to ensure the function of the control.
at <i>n</i> = 2000 rpm		The required control pressure is dependent on rotational speed, working
Controls EP, HD, HW	20 bar above	pressure and the spring assembly of the stroking piston.
	case pressure	_
Controls DA, DG, EZ, ET	25 bar above	
	case pressure	
Case pressure at port T		
Continuous differential pressure $\Delta p_{ extsf{T}\  ext{cont}}$	2 bar	Maximum, averaged differential pressure at the shaft seal (case to ambient pressure)
Maximum differential pressure $\Delta p_{\text{T max}}$	see diagram on page 9	Permissible differential pressure at the shaft seal (case to ambient pressure)
Pressure peaks $p_{T}$ peak	10 bar	t < 0.1 s, maximum 1000 pressure peaks permissible

# f v Maximum pressure $p_{\max}$ up to 450 bar and total operating period

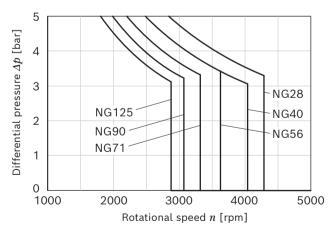


#### ▼ Rate of pressure change R<sub>A max</sub>

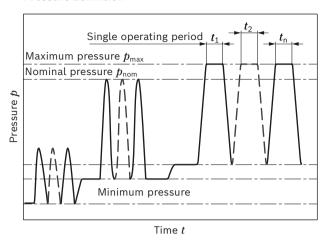


Total operating period =  $t_1 + t_2 + ... + t_n$ 

#### ▼ Maximum differential pressure at the shaft seal



#### ▼ Pressure definition



#### **Notice**

- ► Working pressure range applies when using hydraulic fluids based on mineral oils. Please contact us for values for other hydraulic fluids.
- ► In addition to the hydraulic fluid and the temperature, the service life of the shaft seal is influenced by the rotational speed of the axial piston unit and the case pressure.
- ► The service life of the shaft seal decreases with increasing frequency of pressure peaks and increasing mean differential pressure.
- ► The case pressure must be greater than the external pressure (ambient pressure) at the shaft seal.

#### **Technical data**

Size			NG		28	40	56	71	90	125
Geometric displacem	ent, per revolution	'								
	variable pump		$V_{g\;max}$	cm <sup>3</sup>	28	40	56	71	90	125
	boost pump (at )	<i>b</i> = 20 bar)	$V_{g\;Sp}$	cm <sup>3</sup>	6.1	8.6	11.6	19.6	19.6	28.3
Rotational speed <sup>1)</sup>	maximum at $V_{g}$ m	$_{\rm nax}$ and $\Delta p = 0$ bar	$n_{nom}$	rpm	4250	4000	3600	3300	3050	2850
	limited maximun	1 <sup>2)</sup>	$n_{max1}$	rpm	4500	4200	3900	3600	3300	3250
	intermittent max	imum <sup>3)</sup>	$n_{max2}$	rpm	5000	5000	4500	4100	3800	3450
	minimum		$n_{min}$	rpm	500	500	500	500	500	500
Flow	at $n_{nom}$ and $V_{gma}$	x	$q_{\scriptscriptstyle ee}$	l/min	119	160	202	234	275	356
Power <sup>4)</sup>	at $n_{nom},V_{gmax}$ an	d Δp = 400 bar	P	kW	79	107	134	156	183	238
Torque <sup>4)</sup>	with $V_{gmax}$ and	$\Delta p$ = 400 bar	M	Nm	178	255	357	452	573	796
		$\Delta p$ = 100 bar	M	Nm	45	64	89	113	143	199
Rotary stiffness of dr	ive shaft	S	с	kNm/rad	31.4	69	80.8	98.8	158.1	218.3
		T	с	kNm/rad	-	-	95	120.9	-	252.1
		A	с	kNm/rad	-	79.6	95.8	142.4	176.8	256.5
		Z	с	kNm/rad	32.8	67.5	78.8	122.8	137	223.7
		U	с	kNm/rad	_	50.8	-	_	107.6	-
Moment of inertia of	the rotary group		$J_{\sf TW}$	kgm <sup>2</sup>	0.0022	0.0038	0.0066	0.0097	0.0149	0.0232
Maximum angular acc	celeration <sup>5)</sup>		α	rad/s²	38000	30000	24000	21000	18000	14000
Case volume			V	l	0.9	1.1	1.5	1.3	1.5	2.1
Weight (without thro	ugh drive) approx. <sup>6)</sup>		m	kg	29	31	38	50	60	80

#### **Notice**

- ► Theoretical values, without efficiency and tolerances; values rounded
- ▶ Operation above the maximum values or below the minimum values may result in a loss of function, a reduced service life or in the destruction of the axial piston unit. Bosch Rexroth recommends testing the loads by means of experiment or calculation / simulation and comparison with the permissible values.

Determination	on of the	e op	erating character	istics	
Flow	$q_{\scriptscriptstyle ee}$	=	$\frac{V_{\rm g} \times n \times \eta_{\rm v}}{1000}$		[l/min]
Torque	M	=	$\frac{V_{\rm g} \times \Delta p}{20 \times \pi \times \eta_{\rm hm}}$		[Nm]
Power	P	=	$\frac{2 \pi \times M \times n}{60000} =$	$\frac{q_{\rm v} \times \Delta p}{600 \times \eta_{\rm t}}$	[kW]

#### Key

 $V_{\rm g}$  Displacement per revolution [cm $^3$ ]

 $\Delta p$  Differential pressure [bar]

n Rotational speed [rpm]

 $\eta_{\rm v}$  Volumetric efficiency

 $\eta_{
m hm}$  Hydraulic-mechanical efficiency

 $\eta_{\rm t}$  Total efficiency ( $\eta_{\rm t}$  =  $\eta_{\rm v} \times \eta_{\rm hm}$ )

- 1) The values are applicable:
  - for the optimum viscosity range from  $v_{\rm opt}$  = 36 to 16 mm<sup>2</sup>/s
  - for hydraulic fluid based on mineral oils (for HF hydraulic fluids, observe the technical data in 90225)
- 2) Valid at half corner power (e.g. at  $V_{\rm g\ max}$  and  $p_{\rm nom}/2$ )
- 3) Valid at  $\Delta p$  = 70 to 150 bar or  $\Delta p$  < 300 bar and t < 0.1 s
- 4) Without boost pump

5) The data are valid for values between the minimum required and maximum permissible rotational speed.

Valid for external excitation (e.g. diesel engine 2 to 8 times rotary frequency; cardan shaft twice the rotary frequency).

The limit value is only valid for a single pump.

The load capacity of the connection parts must be considered.

6) Weight may vary by equipment.

# Permissible radial and axial loading of the drive shaft

#### ▼ Splined shaft DIN 5480

Size		NG		28	40	40	56	56	71	71
Drive shaft				W25	W30	W35	W30	W35	W35	W40
Maximum radial force	$\downarrow^{F_{q}}$	$F_{q\;max}$	N	3030	3608	3092	5051	4329	5489	4803
at distance a (to the shaft collar)	a	a	mm	17.5	17.5	20	17.5	20	20	22.5
Maximum axial force	F <sub>ax</sub> +	+ F <sub>ax max</sub>	N	1557	2120	2120	2910	2910	4242	4242
waxiiiuiii axlat lorce	Fax_←	- F <sub>ax max</sub>	N	417	880	880	1490	1490	2758	2758
Size		NG		90	90	125	125			
Drive shaft				W35	W45	W40	W45			
Maximum radial force	$\downarrow^{F_{q}}$ $\vdash$	F <sub>q max</sub>	N	6957	5411	8455	7516			
at distance a (to the shaft collar)	a	a	mm	20	25	22.5	25			
Maximum axial force	<sub>E</sub> +→	+ F <sub>ax max</sub>	N	4330	4330	6053	6053			
	$F_{ax} \overset{+}{\longleftarrow} \overset{-}{\longleftarrow}$	- F <sub>ax max</sub>	N	2670	2670	3547	3547			

# ▼ Splined shaft ANSI B92.1a

Size		NG		28	40	40	56	56	71	71
Drive shaft	,		in	1	1	1 1/4	1 1/4	1 3/8	1 1/4	1 3/8
Maximum radial force	$\downarrow^{F_{q}}$	$F_{\sf q\ max}$	N	2983	4261	3409	4772	4338	6050	5500
at distance a (to the shaft collar)	a	a	mm	19	19	24	24	24	24	24
Maximum axial force	F <sub>ax</sub> +	+ F <sub>ax max</sub>	N	1557	2120	2120	2910	2910	4242	4242
Maximum axial force	rax_ ← ☐	- F <sub>ax max</sub>	N	417	880	880	1490	1490	2758	2758
Size		NG		90	90	125	125			
Drive shaft			in	1 1/4	1 3/4	1 3/4	2			
Maximum radial force	↓ <sup>F</sup> q ⊢	$F_{q\;max}$	N	7670	5478	7609	6658			
at distance a (to the shaft collar)	a	a	mm	24	33.5	33.5	40			
Maximum axial force	F <sub>ax</sub> +	+ F <sub>ax max</sub>	N	4330	4330	6053	6053			
	F ax _ ←	- F <sub>ax max</sub>	N	2670	2670	3547	3547			

#### Notice

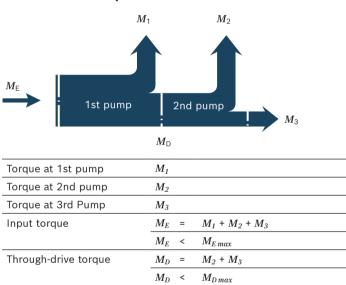
- ► The axial and radial loading generally influence the bearing service life.
- ► Special requirements apply in the case of belt drive and cardan shaft. Please contact us.

# 12

# Permissible input and through-drive torques

Size		NG		28	40	56	71	90	125
Torque at $V_{\rm g\ max}$ and $\Delta p$ = 40	0 bar <sup>1)</sup>	M	Nm	178	255	357	452	573	796
Max. input torque on drive s	haft <sup>2)</sup>								
DIN 5480	Z	$M_{E\;max}$	Nm	352	522	522	912	912	1460
				W25	W30	W30	W35	W35	W40
	Α	$M_{E\;max}$	Nm	-	912	912	1460	2190	2190
					W35	W35	W40	W45	W45
ANSI B92.1a (SAE J744)	S	$M_{E\;max}$	Nm	314	602	602	602	1640	1640
			in	1	1 1/4	1 1/4	1 1/4	1 3/4	1 3/4
	Т	$M_{E\;max}$	Nm	-	-	970	970	-	2670
			in	-	-	1 3/8	1 3/8	-	2
	U <sup>3)</sup>	$M_{E\;max}$	Nm	-	314	-	-	602	-
			in	-	1	-	-	1 1/4	-
Maximum through-drive torq	ue <sup>4)</sup>	$M_{D\;max}$	Nm	231	314	521	660	822	1110

#### **▼** Distribution of torques



<sup>1)</sup> Efficiency not considered

<sup>2)</sup> For drive shafts free of radial force

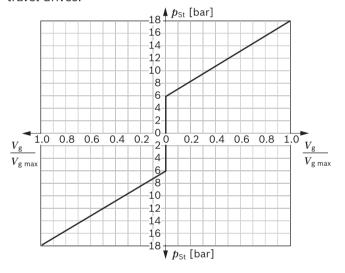
<sup>3)</sup> Shaft "U" is only permissible as a drive shaft for the 2nd pump in a combination pump of the same size.

<sup>4)</sup> Note maximum input torque for shaft S!

# HD - Proportional control, hydraulic, pilot-pressure related

The output flow of the pump is infinitely variable between 0 and 100%, proportional to the difference in pilot pressure applied to the two pilot signal ports ( $\mathbf{Y}_1$  and  $\mathbf{Y}_2$ ). The flow is reversible, depending on pilot pressure side  $\mathbf{Y}_1$  and  $\mathbf{Y}_2$ . The pilot pressure or the pilot pressure difference acts as a setpoint force on the control spool. It then directs control oil into and out of the stroking cylinder to adjust pump displacement according to the setpoint value. The mechanical feedback lever connected to the stroking piston closes the control circuit via a force comparison with the hydraulic setpoint force. In this case, the pump swivel angle is adjusted proportionally to the current difference in pilot pressure.

If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.



Size			28 125
Start of control ( $V_{\rm g0}$ )	$p_{St}$	bar	6
End of control ( $V_{\rm g\ max}$ )	$p_{St}$	bar	18
Maximum required pilot oil volume	$q_{\sf v \; St}$	bar	0.5

# Key

 $V_{\mathrm{g}}$  Displacement

 $V_{\rm g\,0}$  Displacement in neutral position

 $V_{\rm g\; max}$  Maximum displacement

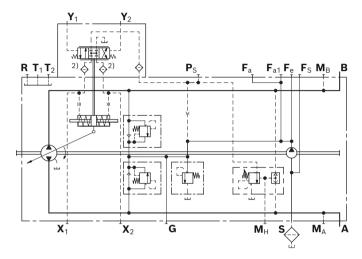
 $p_{St}$  Pilot pressure signal at port  $Y_1$ ,  $Y_2$ 

 $q_{\text{v St}}$  Maximum required pilot oil volume at port  $\mathbf{Y}_1$ ,  $\mathbf{Y}_2$ 

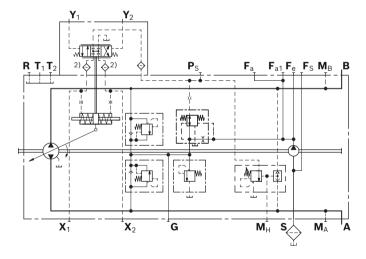
#### **Notice**

For exact neutral position, the pilot pressures  $\mathbf{Y}_1$  and  $\mathbf{Y}_2$  must be completely unloaded via the external control valve or the control pressure difference  $\mathbf{Y}_1$ - $\mathbf{Y}_2$  must be compensated.

#### ▼ Circuit diagram, standard version<sup>1)</sup>



#### ▼ Circuit diagram, version with DA control valve<sup>1)</sup>



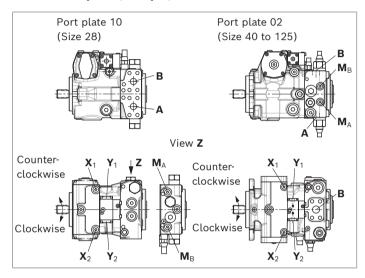
<sup>1)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

<sup>2)</sup> Only sizes 28 to 71 are designed with inlet filtration in  $\boldsymbol{X}_1/\boldsymbol{X}_2$ 

# 14 **A4VG series 32** | Axial piston variable pump HD – Proportional control, hydraulic, pilot-pressure related

Correlation of d	lirection of rotation, cont	rol and flov	v direction	'					
Direction of rota	ation	Clockwise Counter-clockwise							
Size		28 56		71 12	71 125			71 125	
Pilot signal		<b>Y</b> <sub>1</sub>	<b>Y</b> <sub>2</sub>	<b>Y</b> <sub>1</sub>	<b>Y</b> <sub>2</sub>	<b>Y</b> <sub>1</sub>	<b>Y</b> <sub>2</sub>	<b>Y</b> <sub>1</sub>	<b>Y</b> <sub>2</sub>
Control pressure	e	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$
Port plate	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A
02 and 10	Working pressure	M <sub>B</sub>	M <sub>A</sub>	MA	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>
Port plate	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B
03 and 13	Working pressure	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>

# ▼ Position of ports (example)

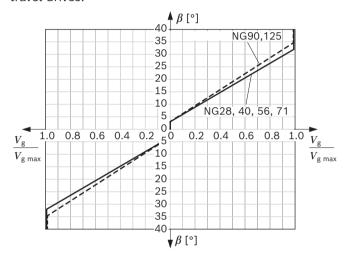


# HW - Proportional control, hydraulic, mechanical servo

The output flow of the pump is infinitely variable between 0 and 100%, proportional to the swivel angle of the control lever.

A feedback lever connected to the stroking piston maintains the pump flow for any given position of the control lever.

If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.



Size		28 71	90 125
Start of control ( $V_{g 0}$ )	β	±3°	±3°
End of control ( $V_{ m g\ max}$ )	β	±32°	±34.5°
Rotational limiter control lever (internal)	β	±38°	±38°

The maximum required torque at the control lever is 170 Ncm. To prevent damage to the HW control module, a positive mechanical stop of 36.5°±1 must be provided for the HW control lever on the customer side.

### Key

$V_{\sigma}$	Displacement
Vg	Displacement

 $V_{\mathrm{g}\,\mathrm{0}}$  Displacement in neutral position

 $V_{\rm g \ max}$  Maximum displacement

 $oldsymbol{eta}$  Swivel angle at the control lever

#### **Notice**

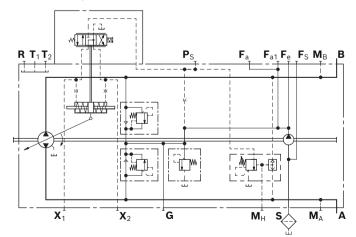
- ▶ Spring-centering enables the pump, depending on pressure and rotational speed, to move automatically to the neutral position ( $V_{\rm g}$  = 0) as soon as there is no longer any torque on the control lever of the HW control module.
- ► As standard delivery, the control lever is oriented toward the through drive (see dimensions).
- ► If necessary, the position of the lever can be changed. The procedure is defined in the instruction manual.
- On delivery, the position of the control lever can deviate from the installation drawing.

#### **Option: Neutral position switch**

The switch contact in the neutral position switch is closed when the control lever on the HW control module is in its neutral position. The switch opens when the control lever is moved out of the central position in either direction. Thus, the neutral position switch provides a monitoring function for drive units that require the control lever at the HW control module to be in the neutral position during certain operating conditions (e.g. starting diesel engine).

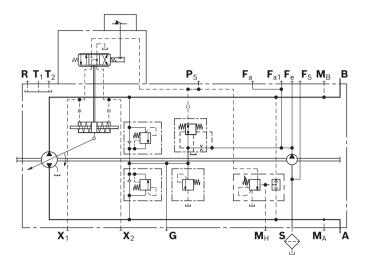
Technical data	
Load capacity	20 A (continuous), without switching operations
Switching capacity	15 A / 32 V (resistive load)
	4 A / 32 V (inductive load)
Connector version	DEUTSCH DT04-2P-EP04
	(mating connector, see page 86)

#### ▼ Circuit diagram, standard version¹)



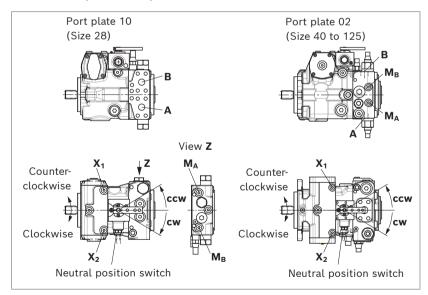
#### 16

# ▼ Circuit diagram, version with DA control valve and neutral position switch<sup>1)</sup>



Correlation of d	lirection of rotation, cont	rol and flov	v direction					'		
Direction of rotation		Clockwis	ie .	·		Counter-	Counter-clockwise			
Size		28 56		71 125	5	28 56		71 125		
Lever direction <sup>2)</sup>		ccw	cw	ccw	cw	ccw	cw	ccw	cw	
Control pressure		$\mathbf{X}_2$	<b>X</b> <sub>1</sub>							
Port plate	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B	
02 and 10	Working pressure	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	MA	M <sub>B</sub>	MA	M <sub>A</sub>	M <sub>B</sub>	
Port plate	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A	
03 and 13	Working pressure	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	

#### ▼ Position of ports (example)



<sup>1)</sup> Size 28 without port  $\boldsymbol{F}_{a1}$  and  $\boldsymbol{F}_{S}$ 

<sup>2)</sup> ccw = counter-clockwise, cw = clockwise

# DA - Automatic control, speed related

The DA closed loop control is an engine speed-dependent system for travel drives. The built-in DA control valve generates a pilot pressure that is proportional to pump drive speed (of the motor). This pilot pressure is directed to the stroking cylinder of the pump by an electromagnetically actuated 4/3-way directional valve. The pump displacement is infinitely variable in each flow direction and is influenced by both pump drive speed and system pressure. The flow direction (i.e. machine moving forward or backward) is determined by either solenoid **a** or **b** being activated.

Increasing the pump drive speed generates a higher pilot pressure from the DA control valve, with a subsequent increase in pump flow.

Depending on the selected operating characteristics of the pump, increasing the system pressure (i.e. machine load) causes the pump to swivel back towards a smaller displacement. An overload protection for the engine (against stalling) is achieved by combining this pressure-dependent reduction in pump stroke with a reduction in pilot pressure as the engine speed drops. Any additional power requirement, e.g. for hydraulic functions from attachments, could cause the engine rotational speed to drop further. This will cause a further reduction in pilot pressure and thus of the pump displacement. Automatic power distribution and full exploitation of the available power are achieved in this way, both for the travel drive and for the implement hydraulics, with priority given to the implement hydraulics. Various override options are available for DA control function to allow controlled operation of the implement hydraulics with high rotational speeds at reduced travel speed.

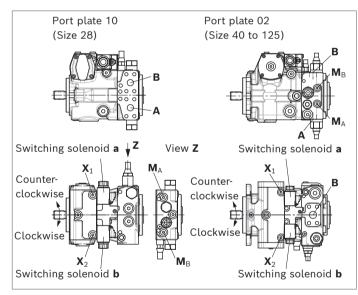
The DA control valve can also be used in pumps with EP, DG, HW and HD control modules to protect the combustion engine against overload.

#### **Notice**

DA closed loop control is only suitable for certain types of travel drive systems and requires review of the motor and vehicle parameters to ensure that the pump is used correctly and that machine operation is safe and efficient. We recommend that all DA applications be reviewed by a Bosch Rexroth application engineer.

Technical data, switching solenoid	DA1	DA2
Voltage	12 V (±20%)	24 V (±20%)
Neutral position $V_{\rm g}$ = 0	de-energized	de-energized
Position $V_{\rm g\ max}$	current switched on	current switched on
Nominal resistance (at 20 °C)	5.5 Ω	21.7 Ω
Nominal power	26.2 W	26.5 W
Minimum required active current	1.32 A	0.67 A
Duty cycle	100%	100%
Type of protection: see connector ve	ersion page 86	

#### **▼** Position of ports (example)

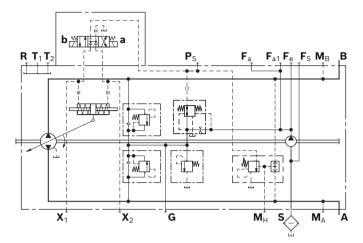


Correlation of o	lirection of rotation, cont	rol and flov	v direction							
Direction of rota	ation	Clockwis	Clockwise			Counter-	Counter-clockwise			
Size		28 56		71 12	5	28 56		71 125	5	
Actuation of switching solenoid		а	b	а	b	a	b	а	b	
Control pressure	e	<b>X</b> <sub>2</sub>	<b>X</b> <sub>1</sub>							
Port plate	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B	
02 and 10	Working pressure	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	MA	M <sub>A</sub>	M <sub>B</sub>	
Port plate	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A	
03 and 13	Working pressure	M <sub>B</sub>	MA	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	

#### DA..2 - DA control valve, fixed setting

Pilot pressure is generated in relation to drive speed.

#### ▼ Circuit diagram DA control valve, fixed setting, DA1D2/ DA2D2¹¹



# DA..3 - DA control valve, mechanically adjustable with position lever

Pilot pressure is generated in relation to drive speed.

Any reduction of pilot pressure possible, independently of drive speed, through mechanical actuation of the position lever (inch function).

The maximum permissible actuation torque at the position lever is  $M_{\rm max}$  = 4 Nm.

In the standard version, the position lever is oriented towards the control module, see dimension.

The maximum angle of rotation is 70°.

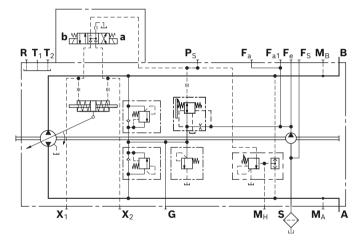
#### DA..3R

Direction of actuation of the position lever: clockwise

#### DA..3L

Direction of actuation of the position lever: counterclockwise

#### ▼ Circuit diagram DA1D3/DA2D3<sup>1)</sup>



# DA..7 - DA control valve, fixed setting, ports for pilot control device as inch valve

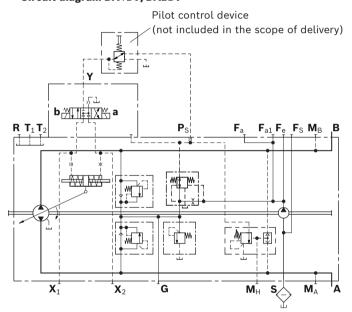
Any reduction of the pilot pressure possible, independent of the drive speed is achieved by the mechanical actuation of the pilot control device.

The pilot control device is installed separately from the pump (for example in the driver's cabin) and connected to the pump by two hydraulic control lines via ports  $\mathbf{P}_{S}$  and  $\mathbf{Y}$ .

A suitable pilot control device must be ordered separately and is not included in the scope of delivery.

Notice: Rotary inch valves, see page 87.

#### ▼ Circuit diagram DA1D7/DA2D7¹)



# DA..8 – DA control valve, fixed setting and hydraulic inch valve mounted

Only for pumps with DA control module

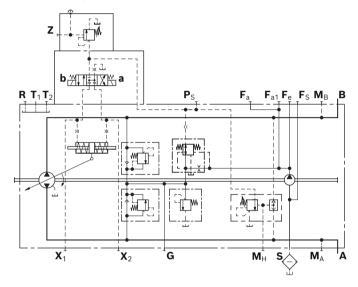
- ► Version with throttle valve size 28, 40, 56, 71
- ▶ Version with pressure reducing valve size 90, 125

Permits reduction of the pilot pressure, independently of the drive speed, hydraulically controlled (port **Z**).

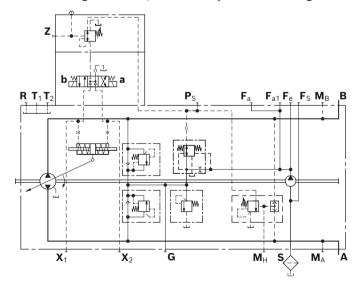
The hydraulic inch valve at port **Z** is controlled with mineral oil-based hydraulic fluid.

Maximum permissible pilot pressure at port Z: 80 bar

#### ▼ Circuit diagram DA1D8/DA2D8 with throttle valve<sup>1)</sup>



#### ▼ Circuit diagram DA1D8/DA2D8 with pressure reducing valve<sup>1)</sup>



# DG - Hydraulic control, direct operated

With the direct operated hydraulic control (DG), the output flow of the pump is controlled by a hydraulic control pressure, applied directly to the stroking piston through either port  $\mathbf{X}_1$  or  $\mathbf{X}_2$ .

Flow direction is determined by which control pressure port is pressurized.

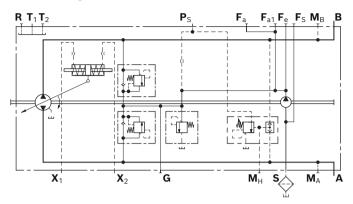
Pump displacement is infinitely variable and proportional to the applied control pressure, but is also influenced by system pressure and pump drive speed.

In order to use the optional built-in pressure cut-off, port  $\mathbf{P}_S$  must be used for the selected control module as source of the control pressure  $\mathbf{X}_1$  and  $\mathbf{X}_2$  generated on the customer side.

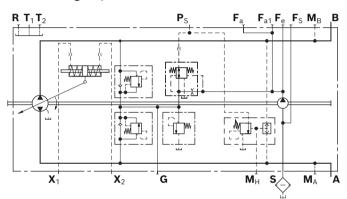
See page 77 for a functional description of the pressure cut-off.

Maximum permissible control pressure: 40 bar Use of the DG control requires a review of the engine and vehicle parameters to ensure that the pump is set up correctly. We recommend that all DG applications be reviewed by a Bosch Rexroth application engineer. If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.

#### ▼ Circuit diagram, standard version<sup>1)</sup>



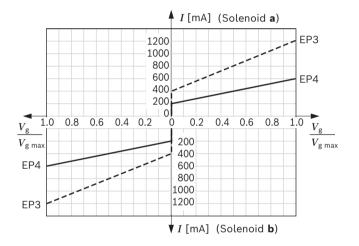
#### ▼ Circuit diagram, version with DA control valve1)



Correlation of di	irection of rotation, cont	rol and flov	direction							
Direction of rotat	tion	Clockwis	е			Counter-	clockwise			
Size		28 56		71 125	71 125		28 56		71 125	
Control pressure		<b>X</b> <sub>1</sub>	<b>X</b> <sub>2</sub>							
Port plate	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A	
02 and 10	Working pressure	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	MA	
Port plate 03 and 13	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to E	
	Working pressure	MA	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	MA	MA	M <sub>B</sub>	

# EP - Proportional control, electric

The output flow of the pump is infinitely variable in the range between 0 to 100%, proportional to the electrical current supplied to solenoid. The flow is reversible, depending on solenoid side **a** or **b**. The magnetic force acts as a setpoint value on the control spool. It then directs control oil into and out of the stroking cylinder to adjust pump displacement according to the setpoint value. The mechanical feedback lever connected to the stroking piston closes the control circuit via a force comparison with the magnetic force. In this case, the pump swivel angle is adjusted proportionally to the control current. If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.



#### **Notice**

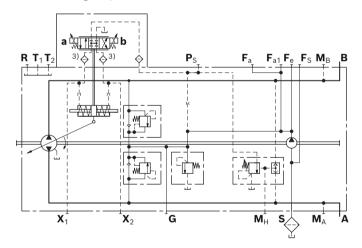
The proportional solenoids do not have manual override. Proportional solenoids with manual override and spring return are available on request.

Technical data, proportional solenoid	EP3	EP4
Voltage	12 V (±20%)	24 V (±20%)
Control current		
Start of control at $V_{\rm g}$ = 0	400 mA	200 mA
End of control at $V_{g\ max}$	1200 mA	600 mA
Current limit	1.54 A	0.77 A
Nominal resistance (at 20 °C)	5.5 Ω	22.7 Ω
Dither		
Frequency	100 Hz	100 Hz
Minimum oscillation range <sup>1)</sup>	240 mA	120 mA
Duty cycle	100%	100%
Type of protection: see connector v	ersion page 86	

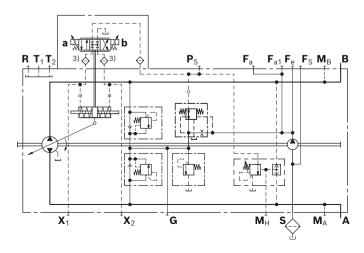
Various BODAS controllers with application software and amplifiers are available for controlling the proportional solenoids.

Further information can also be found on the Internet at www.boschrexroth.com/mobile-electronics

#### ▼ Circuit diagram, standard version<sup>2)</sup>



#### ▼ Circuit diagram, version with DA control valve<sup>2)</sup>



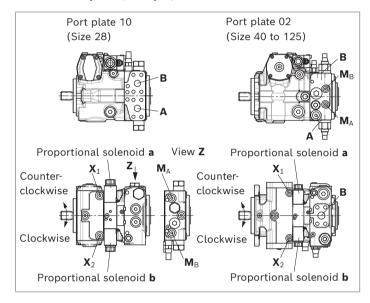
<sup>1)</sup> Minimum required oscillation range of the control current  $\Delta I_{\text{p-p}}$  (peak to peak) within the respective control range (start of control to end of control)

<sup>2)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

<sup>3)</sup> Only sizes 28 to 71 are designed with inlet filtration in  $\mathbf{X}_1/\mathbf{X}_2$ 

Correlation of o	direction of rotation, cont	rol and flov	direction				·	·	
Direction of rota	ation	Clockwise Counter-clockwise							
Size 1)		28 56		71 125	5	28 56		71 125	5
Actuation of proportional solenoid		а	b	а	b	а	b	а	b
Control pressure		<b>X</b> <sub>1</sub>	<b>X</b> <sub>2</sub>	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	<b>X</b> <sub>2</sub>
Port plate	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A
02 and 10	Working pressure	M <sub>B</sub>	M <sub>A</sub>	MA	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>
Port plate 03 and 13	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B
	Working pressure	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>

# ▼ Position of ports (example)



 $_{
m 1)}\,$  Available port plates per size, see type code position 15

# **EZ - Two-point control, electric**

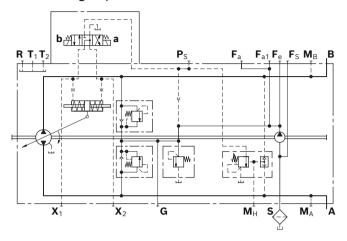
By actuating either switching solenoid  $\mathbf{a}$  or  $\mathbf{b}$ , internal control pressure is applied directly to the stroking piston and the pump swivels to maximum displacement.

The EZ control enables pump flow to be switched between  $V_{\rm g}$  = 0 and  $V_{\rm g\;max}.$ 

Flow direction is determined by which solenoid is energized.

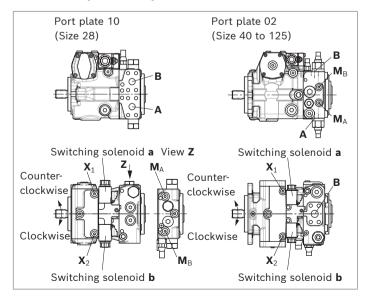
Technical data, switching solenoid	EZ1	EZ2
Voltage	12 V (±20%)	24 V (±20%)
Neutral position $V_{\rm g}$ = 0	de-energized	de-energized
Position $V_{\rm g\ max}$	current switched on	current switched on
Nominal resistance (at 20 °C)	5.5 Ω	21.7 Ω
Nominal power	26.2 W	26.5 W
Minimum required active current	1.32 A	0.67 A
Duty cycle	100%	100%
Type of protection: see connector	version page 86	

#### ▼ Circuit diagram, standard version¹)



Correlation of o	direction of rotation, cont	rol and flov	v direction	'	'	'	'	'	
Direction of rota	ation	Clockwis	Clockwise		Counter-clockwise				
Size		28 56 71 125		28 56 71 125		5			
Actuation of swi	tching solenoid	а	b	а	b	a	b	а	b
Control pressure	e	<b>X</b> <sub>2</sub>	<b>X</b> <sub>1</sub>						
Port plate	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B
02 and 10	Working pressure	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>
Port plate 03 and 13	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A
	Working pressure	M <sub>B</sub>	MA	MA	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>

#### ▼ Position of ports (example)



<sup>1)</sup> Size 28 without port  $\boldsymbol{F}_{a1}$  and  $\boldsymbol{F}_{S}$ 

# ET - electronic control, direct-operated

# ETA/ETB – two pressure reducing valves, prepared for BODAS Software

The ETA/ETB control is optimized for electronic drives and is intended to be used together with the BODAS software. Here, all relevant configuration options have already been predefined and ensure an optimal interaction of pump and software thanks to the standardization. The pump function is largely determined by the software used.

The output flow of the pump is infinitely variable in the range between 0 and 100 %. Depending on the preselected current I at solenoids  $\mathbf{a}$  and  $\mathbf{b}$  of the pressure reducing valves, the stroking cylinder of the pump is proportionally supplied with control pressure. The two control pressures  $\mathbf{X}_1$  and  $\mathbf{X}_2$  can be controlled independently. The pump displacement that arises at acertain control current is dependent on the rotational speed and working pressure of the pump. A different flow direction is associated with each pressure reducing valve.

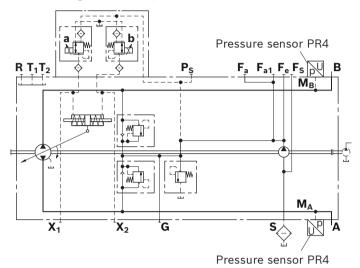
Maximum permissible control pressure at port Ps: 40 bar.

Technical data, pressure reducing	ETA <sup>1)</sup> ETB <sup>1)</sup>	ETA <sup>2)</sup> ETB <sup>2)</sup>				
valve	NG28, 40	NG125				
On-board voltage in the vehicle	12 V 24 V	12 V 24 V				
Permissible voltage $\it U$	9.6 28.8 V	9.6 28.8 V				
Current limit	1.8 A	1.45 A				
Nominal resistance (at 20 °C)	2.4 Ω	4.05 Ω				
Dither						
Frequency	100 Hz	100 Hz				
minimum oscillation range <sup>3)</sup>	360 mA	250 mA				
Duty cycle	100 %	100 %				
Type of protection: see connector version page 86						

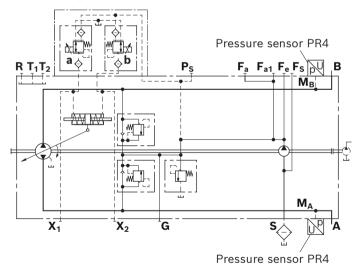
#### **Notice**

All control-relevant data are already stored in the software.

#### ▼ Circuit diagram ETA/ETB, sizes 28 and 40<sup>4)</sup>



#### ▼ Circuit diagram ETA/ETB, size 125



<sup>1)</sup> For further information on the pressure reducing valve, see data sheet 58032.

**Notice**: The leakage flow and the control flow differ from the parameter in data sheet 58032.

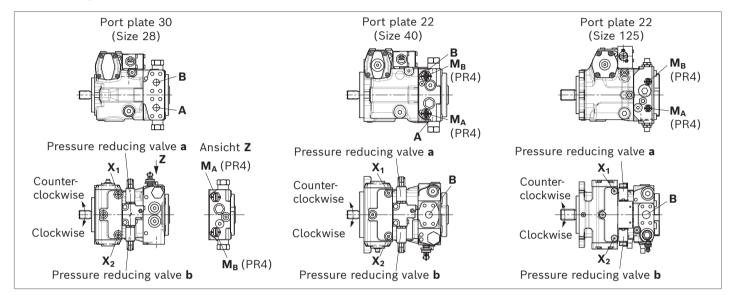
2) For further information on the pressure reducing valve, see data sheet 64659.

**Notice**: The leakage flow and the control flow differ from the parameter in data sheet 64659.

- 3) Minimum required oscillation range of the control current  $\Delta I_{\text{p-p}}$  (peak to peak) within the respective control range (start of control to end of control)
- 4) Size 28 without port  $\boldsymbol{F}_{a1}$  and  $\boldsymbol{F}_{S}$

Correlation of direction of rotation,	control and	flow direct	ion					
Direction of rotation	Clockwise			Counter-o	Counter-clockwise			
Size	28 40		125		28 40		125	
Actuation of pressure reducing valve	a	b	а	b	а	b	а	b
Control pressure	<b>X</b> <sub>1</sub>	<b>X</b> <sub>2</sub>	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$
Flow direction	A to B	B to A	<b>B</b> to <b>A</b>	A to B	B to A	A to B	A to B	B to A
Working pressure	M <sub>B</sub>	MA	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>

#### **▼** Position of ports

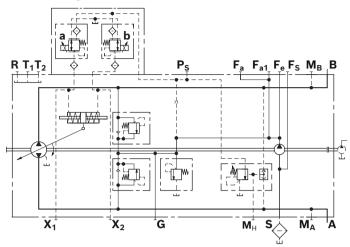


#### ET3/ET4 und ET7/ET8 - two pressure reducing valves

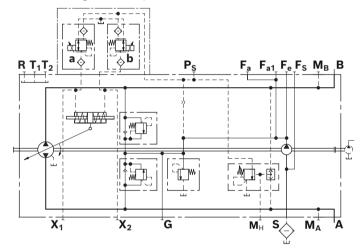
The output flow of the pump is infinitely variable in the range between 0 and 100 %. Depending on the preselected current I at solenoids  $\mathbf{a}$  and  $\mathbf{b}$  of the pressure reducing valves, the stroking cylinder of the pump is proportionally supplied with control pressure. The two control pressures  $\mathbf{X}_1$  and  $\mathbf{X}_2$  can be controlled independently. The pump displacement that arises at acertain control current is dependent on the rotational speed and working pressure of the pump. A different flow direction is associated with each pressure reducing valve. Maximum permissible control pressure at port  $\mathbf{P}_{S}$ : 40 bar.

Technical data, pressure reducing	FT3 <sup>1)</sup>	ET4 <sup>1)</sup>	FT72)	ET8 <sup>2)</sup>
valve	LIST		L17	LIO
On-board voltage in the vehicle	12 V	24 V	12 V	24 V
Permissible voltage $\it U$	9.6	9.6 28.8 V		28.8 V
Current limit	1.8 A 1.		45 A	
Nominal resistance (at 20 °C)	2.4 Ω		4.05 Ω	
Dither				
Frequency	100 Hz		100 Hz	
Minimum oscillation range <sup>3)</sup>	360 mA		250 mA	
Duty cycle	100%		100%	
Type of protection: see connector ver	sion pag	re 86		

#### ▼ Circuit diagram ET3/4, standard version<sup>4)</sup>



#### ▼ Circuit diagram ET7/8, standard version



<sup>1)</sup> For further information on the pressure reducing valve, see data sheet 58032.

**Notice**: The leakage flow and the control flow differ from the parameter in data sheet 58032.

<sup>2)</sup> For further information on the pressure reducing valve, see data sheet 64659.

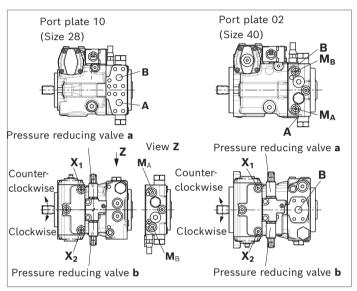
**Notice**: The leakage flow and the control flow differ from the parameter in data sheet 64659.

<sup>3)</sup> Minimum required oscillation range of the control current  $\Delta I_{\text{p-p}}$  (peak to peak) within the respective control range (start of control to end of control)

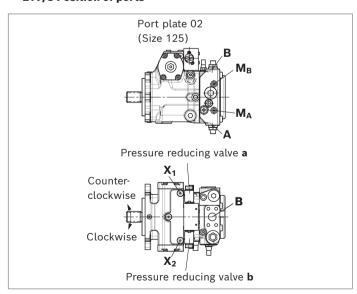
<sup>4)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

Correlation of o	direction of rotation, cont	rol and flov	v direction		· ·				
Direction of rota	ation	Clockwis	Clockwise		Counter-clockwise				
Size <sup>1)</sup>		28 40		125		28 40	28 40 125		
Actuation of pre	ssure reducing valve	а	b	а	b	a	b	a	b
Control pressur	e	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$	<b>X</b> <sub>1</sub>	<b>X</b> <sub>2</sub>	<b>X</b> <sub>1</sub>	<b>X</b> <sub>2</sub>	<b>X</b> <sub>1</sub>	$\mathbf{X}_2$
Port plate	Flow direction	A to B	B to A	B to A	A to B	B to A	A to B	A to B	B to A
02 and 10	Working pressure	M <sub>B</sub>	MA	MA	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>
Port plate 03 and 13	Flow direction	B to A	A to B	A to B	B to A	A to B	B to A	B to A	A to B
	Working pressure	M <sub>A</sub>	M <sub>B</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>

# ▼ ET3/4 Position of ports (example)



### ▼ ET7/8 Position of ports

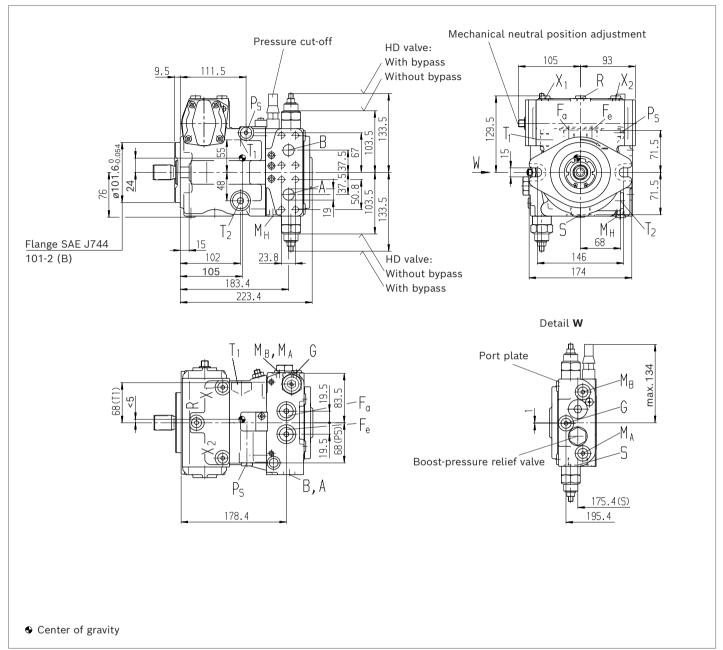


<sup>1)</sup> Depending on the size, different/not all port plates are available, see type code position 15

# Dimensions, size 28

#### **Version without control module**

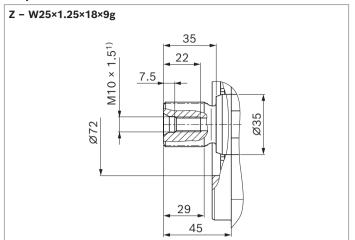
Standard: SAE working port **A** and **B**, same side right, suction port **S** bottom (10)



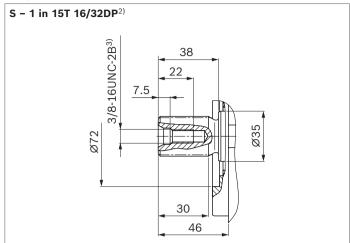
#### **Notice**

Option: SAE working port **A** and **B**, same side left, suction port **S** top (13): Port plate 10 rotated through 180°, installation drawing on request

# ▼ Splined shaft DIN 5480



# ▼ Splined shaft ANSI B92.1a



<sup>1)</sup> Center bore according to DIN 332 (thread according to DIN 13)

 $_{\rm 2)}$  Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>3)</sup> Thread according to ASME B1.1

#### ▼ Connection table for port plate 10 and 13

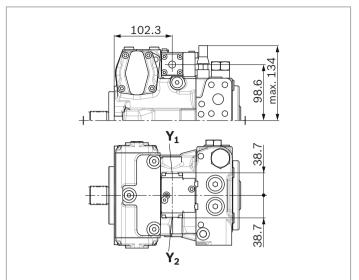
Ports		Standard	Size	$p_{\sf max}$ [bar] $^{4)}$	State <sup>11)</sup>
A, B	Working port Fastening thread	SAEJ518 <sup>5)</sup> DIN 13	3/4 in M10 × 1.5; 17 deep	450	0
S	Suction port	DIN 38528)	M33 × 2; 18 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	3	X <sup>7)</sup>
R	Air bleed port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	3	X
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	X
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice, DG only)	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	0
<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub> <sup>9)</sup>	Stroking chamber pressure port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	X
G	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	Х
Ps	Pilot pressure port	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	Χ
Ps	Pilot pressure port (DA7 only)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
Υ	Pilot pressure port outlet (only DA7)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
$\mathbf{M}_{A},\mathbf{M}_{B}$	Measuring port pressure A, B	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	Χ
$\mathbf{M}_{H}$	Measuring port, high pressure	DIN 3852 <sup>8))</sup>	M12 × 1.5; 12 deep	450	Χ
<b>F</b> <sub>a</sub>	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
<b>F</b> <sub>e</sub>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Х
<b>Y</b> <sub>1</sub> , <b>Y</b> <sub>2</sub>	Pilot pressure port (pilot signal HD only)	DIN 38528)	M14 × 1.5; 12 deep	40	0
Z	Pilot pressure port (inch signal only DA8)	DIN 3852 <sup>8)</sup>	M10 × 1; 8 deep	80	X

#### ▼ Connection table for port plate 30

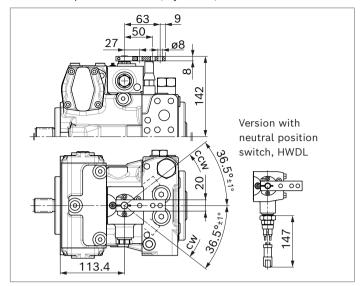
Ports		Standard	Size	$p_{\text{max}}$ [bar] <sup>4)</sup>	State <sup>11)</sup>
A, B	Working port	SAEJ518 <sup>5)</sup>	3/4 in	450	0
	Fastening thread	DIN 13	M10 × 1.5; 17 deep		
S	Suction port	ISO 6149 <sup>10)</sup>	M33 × 2; 19 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	ISO 6149 <sup>10)</sup>	M22 × 1.5; 14 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	ISO 6149 <sup>10)</sup>	M22 × 1.5; 14 deep	3	X <sup>7)</sup>
R	Air bleed port	ISO 6149 <sup>10)</sup>	M12 × 1.5; 12 deep	3	Х
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	ISO 6149 <sup>10)</sup>	M12 × 1.5; 12 deep	40	Х
G	Boost pressure port inlet	ISO 6149 <sup>10)</sup>	M14 × 1.5; 11.5 deep	40	Х
Ps	Pilot pressure port	ISO 6149 <sup>10)</sup>	M14 × 1.5; 12 deep	40	Х
M <sub>A</sub> , M <sub>B</sub>	Measuring port pressure A, B	ISO 6149 <sup>10)</sup>	M14 × 1.5; 11.5 deep	450	Х
<b>F</b> <sub>a</sub>	Boost pressure port inlet	ISO 6149 <sup>10)</sup>	M18 × 1.5; 14.5 deep	40	Х
<b>F</b> <sub>e</sub>	Boost pressure port outlet	ISO 6149 <sup>10)</sup>	M18 × 1.5; 14.5 deep	40	Х

- 4) Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.
- 5) Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.
- 6) Plugged for external boost pressure supply.
- 7) Depending on installation position,  $T_1$  or  $T_2$  must be connected (see also installation instructions on page 89).
- 8) The countersink may be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E
- 9) Optional, see page 79
- 10) The countersink may be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 6149-2
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (observe installation instructions)

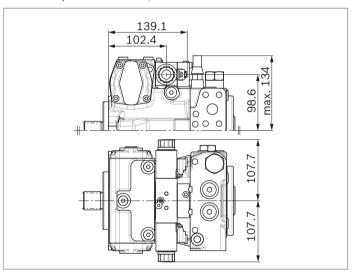
#### ▼ HD - Proportional control, hydraulic, pilot-pressure related



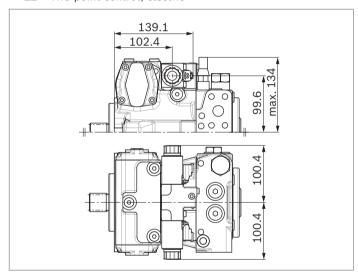
▼ **HW** - Proportional control, hydraulic, mechanical servo



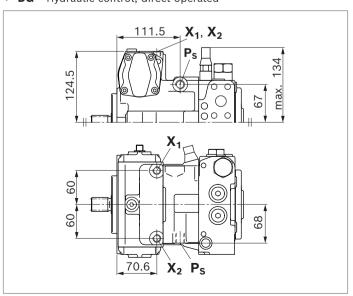
▼ **EP** - Proportional control, electric



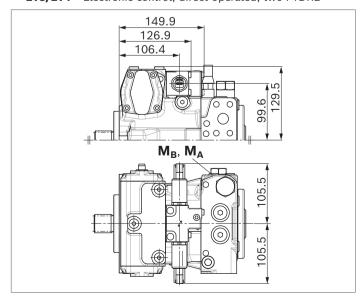
▼ **EZ** – Two-point control, electric



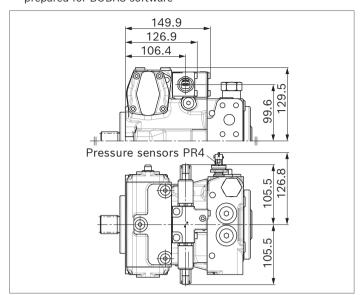
▼ **DG** - Hydraulic control, direct operated



▼ ET3/ET4 - Electronic control, direct operated, two FTDRE

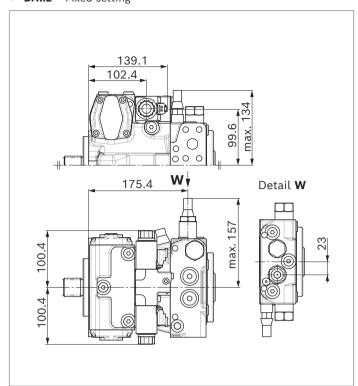


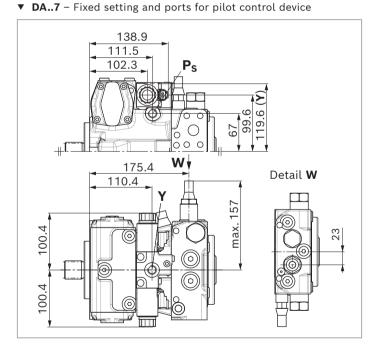
▼ ETA/ETB – Electronic control, direct operated, prepared for BODAS software



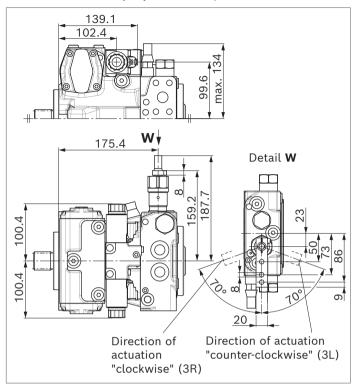
#### **DA** control valve

#### ▼ DA..2 - Fixed setting

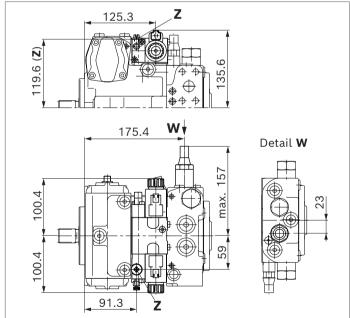




▼ DA..3 - Mechanically adjustable with position lever



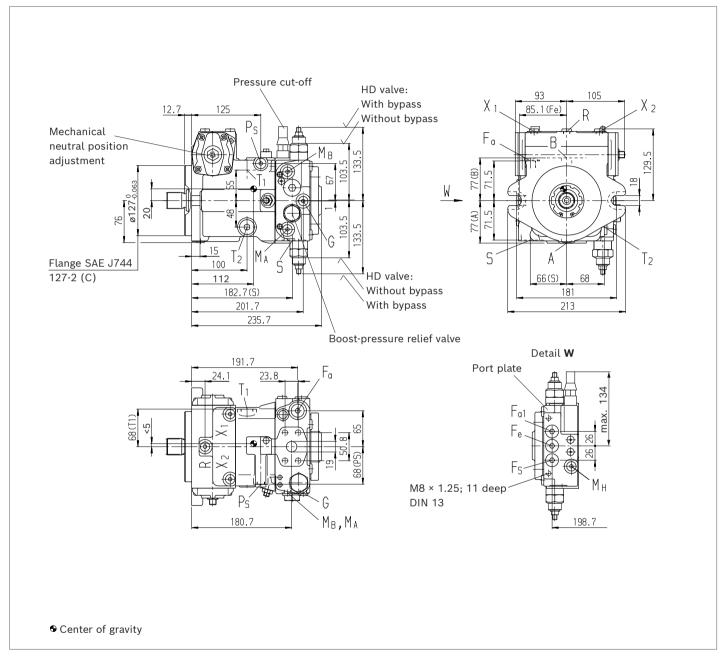
▼ DA..8 - Fixed setting and inch valve mounted



# Dimensions, size 40

#### **Version without control module**

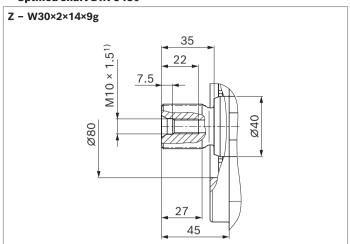
Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (02)



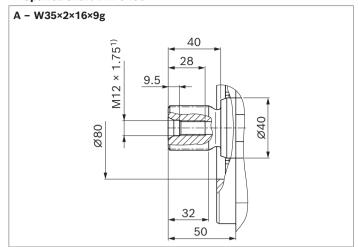
#### **Notice**

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (03), port plate (02) rotated through 180°, installation drawing on request

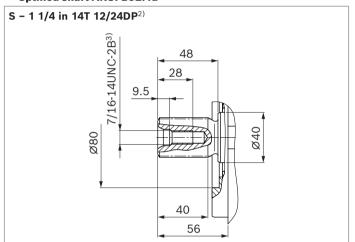
#### ▼ Splined shaft DIN 5480



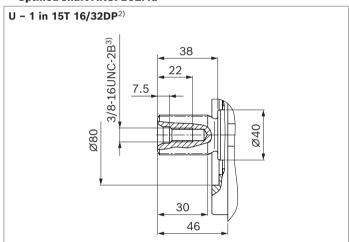
# ▼ Splined shaft DIN 5480



#### ▼ Splined shaft ANSI B92.1a



#### ▼ Splined shaft ANSI B92.1a



<sup>1)</sup> Center bore according to DIN 332 (thread according to DIN 13)

<sup>2)</sup> Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>3)</sup> Thread according to ASME B1.1

#### ▼ Connection table for port plate 02 and 03

Ports		Standard	Size	$m{p}_{\sf max}$ [bar] $^{4)}$	State <sup>12)</sup>
A, B	Working port	SAEJ518 <sup>5)</sup>	3/4 in	450	0
	Fastening thread	DIN 13	M10 × 1.5; 17 deep		
S	Suction port	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	DIN 38528)	M22 × 1.5; 14 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	DIN 38528)	M22 × 1.5; 14 deep	3	X <sup>7)</sup>
R	Air bleed port	DIN 38528)	M12 × 1.5; 12 deep	3	X
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	X
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice, DG only)	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	0
<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub> <sup>9)</sup>	Stroking chamber pressure port	DIN 38528)	M12 × 1.5; 12 deep	40	X
G	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	X
Ps	Pilot pressure port	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	X
Ps	Pilot pressure port (DA7 only)	DIN 38528)	M14 × 1.5; 12 deep	40	0
Υ	Pilot pressure port outlet (only DA7)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring port pressure A, B	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	X
M <sub>H</sub>	Measuring port, high pressure	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	X
<b>F</b> a	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
<b>F</b> a1 <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
<b>F</b> <sub>S</sub> <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
<b>Y</b> <sub>1</sub> , <b>Y</b> <sub>2</sub>	Pilot pressure port (pilot signal HD only)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
Z	Pilot pressure port (inch signal only DA8)	DIN 3852 <sup>8)</sup>	M10 × 1; 8 deep	80	Χ

#### ▼ Connection table for port plate 22

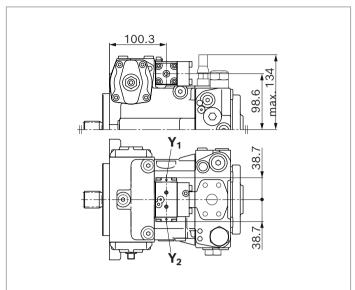
Ports		Standard	Size	$p_{max}$ [bar] $^{4)}$	State <sup>12)</sup>
A, B	Working port	SAEJ518 <sup>5)</sup>	3/4 in	450	0
	Fastening thread	DIN 13	M10 × 1.5; 17 deep		
S	Suction port	ISO 6149 <sup>11)</sup>	M33 × 2; 19 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	ISO 6149 <sup>11)</sup>	M22 × 1.5; 14 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	ISO 6149 <sup>11)</sup>	M22 × 1.5; 14 deep	3	X <sup>7)</sup>
R	Air bleed port	ISO 6149 <sup>11)</sup>	M12 × 1.5; 12 deep	3	Х
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	ISO 6149 <sup>11)</sup>	M12 × 1.5; 12 deep	40	Х
G	Boost pressure port inlet	ISO 6149 <sup>11)</sup>	M14 × 1.5; 11.5 tief	40	Х
Ps	Pilot pressure port	ISO 6149 <sup>11)</sup>	M14 × 1.5; 12 deep	40	Х
M <sub>A</sub> , M <sub>B</sub>	Measuring port pressure A, B	ISO 6149 <sup>11)</sup>	M14 × 1.5; 11.5 deep	450	Х
<b>F</b> <sub>a</sub>	Boost pressure port inlet	ISO 6149 <sup>11)</sup>	M18 × 1.5; 14.5 deep	40	Х
<b>F</b> <sub>a1</sub> <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Х
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Х
<b>F</b> s <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 38528)	M18 × 1.5; 12 deep	40	Χ

- 4) Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.
- 5) Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.
- 6) Plugged for external boost pressure supply.
- 7) Depending on installation position,  $T_1$  or  $T_2$  must be connected (see also installation instructions on page 89).
- 8) The countersink may be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E

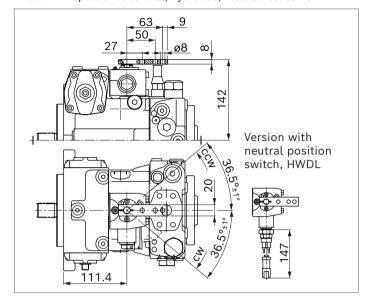
- 9) Optional, see page 79
- 10) The diameter of the countersink deviates from the standard. (For details, see page 82, dimensions of the countersinks)
- 11) The countersink may be deeper than specified in the standard.

  Ports designed for straight stud ends according to EN ISO 6149-2
- 12) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

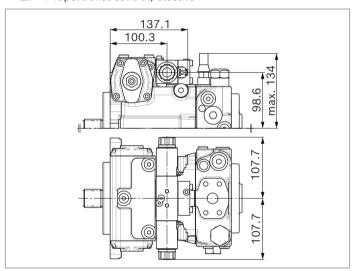
# ▼ HD - Proportional control, hydraulic, pilot-pressure related



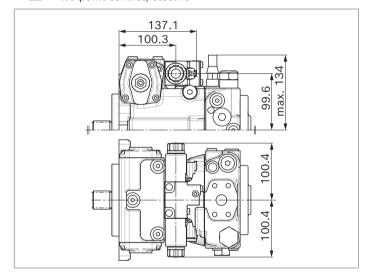
▼ **HW** - Proportional control, hydraulic, mechanical servo



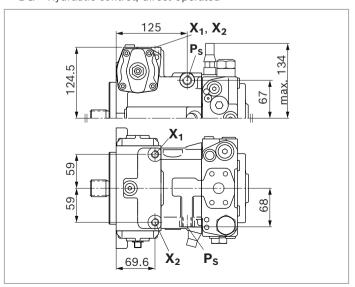
▼ EP - Proportional control, electric



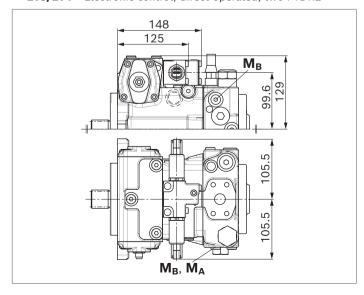
▼ EZ - Two-point control, electric



▼ **DG** - Hydraulic control, direct operated

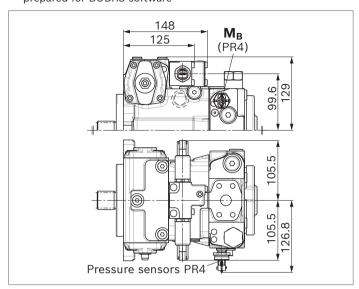


▼ ET3/ET4 - Electronic control, direct operated, two FTDRE



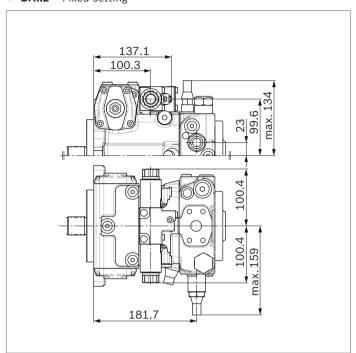
▼ ETA/ETB – Electronic control, direct operated, prepared for BODAS software

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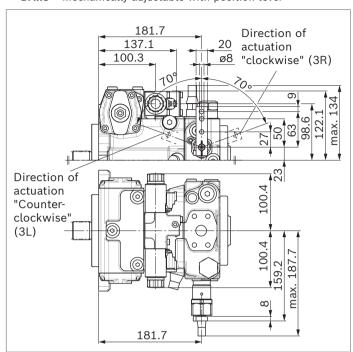


# DA control valve

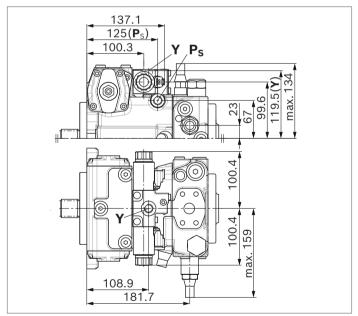
# ▼ DA..2 - Fixed setting



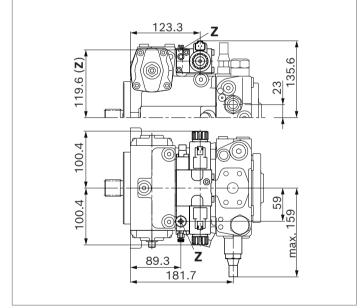
▼ DA..3 - Mechanically adjustable with position lever



▼ DA..7 - Fixed setting and ports for pilot control device



▼ DA..8 - Fixed setting and inch valve mounted

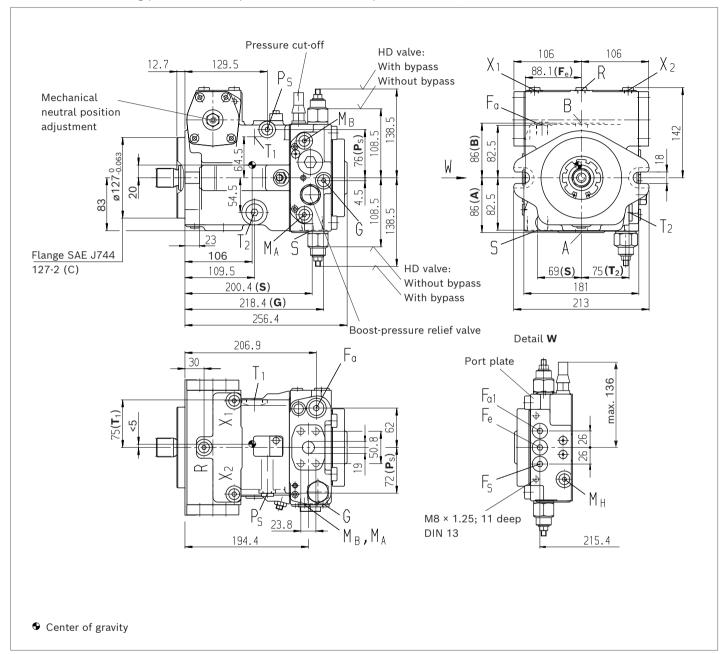


# Dimensions, size 56

40

# **Version without control module**

Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (02)

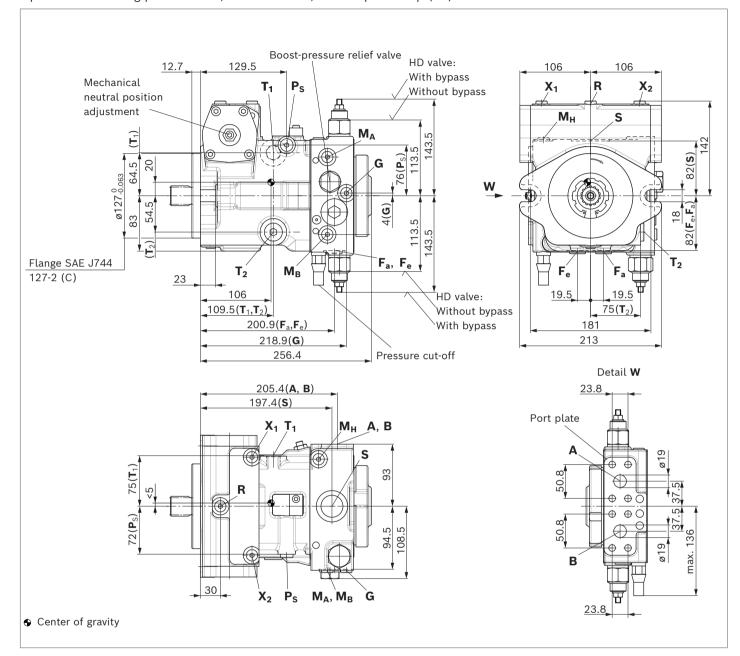


#### **Notice**

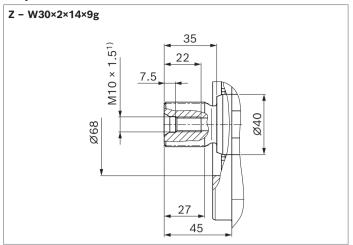
Option: SAE working port **A** and **B** top and bottom, suction port **S** top (03), port plate (02) rotated through 180°, installation drawing on request

#### Version without control module

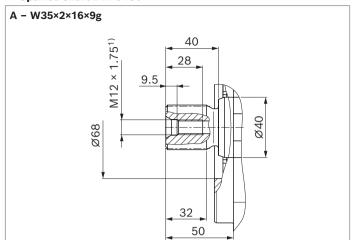
Option: SAE working port **A** and **B**, same side left, suction port **S** top (13)



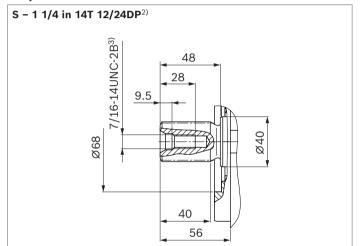
# ▼ Splined shaft DIN 5480



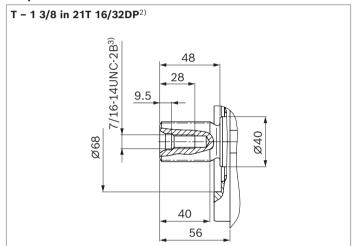
# ▼ Splined shaft DIN 5480



# ▼ Splined shaft ANSI B92.1a



# ▼ Splined shaft ANSI B92.1a



<sup>1)</sup> Center bore according to DIN 332 (thread according to DIN 13)

 $_{\rm 2)}$  Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>3)</sup> Thread according to ASME B1.1

Ports		Standard	Size	$p_{max}$ [bar] <sup>4)</sup>	State <sup>11)</sup>
A, B	Working port	SAEJ518 <sup>5)</sup>	3/4 in	450	0
	Fastening thread	DIN 13	M10 × 1.5; 17 deep		
S	Suction port	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	3	X <sup>7)</sup>
R	Air bleed port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	3	Х
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	Χ
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice, DG only)	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	0
<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub> <sup>9)</sup>	Stroking chamber pressure port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	Х
G	Boost pressure port inlet Working port A/B top and bottom	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	Х
	Working port A/B lateral	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	Х
Ps	Pilot pressure port	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	Х
Ps	Pilot pressure port (DA7 only)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
Υ	Pilot pressure port outlet (only DA7)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring port pressure A, B	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	Х
M <sub>H</sub>	Measuring port, high pressure	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	Х
<b>F</b> a	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Х
<b>F</b> a1 <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 38528)	M18 × 1.5; 12 deep	40	Х
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Х
<b>F</b> s <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Χ
<b>Y</b> <sub>1</sub> , <b>Y</b> <sub>2</sub>	Pilot pressure port (pilot signal HD only)	DIN 38528)	M14 × 1.5; 12 deep	40	0
Z	Pilot pressure port (inch signal only DA8)	DIN 3852 <sup>8)</sup>	M10 × 1; 8 deep	80	Х

<sup>4)</sup> Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

<sup>5)</sup> Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

 $_{\rm 6)}\,$  Plugged for external boost pressure supply.

<sup>7)</sup> Depending on installation position,  $\mathbf{T}_1$  or  $\mathbf{T}_2$  must be connected (see also installation instructions on page 89).

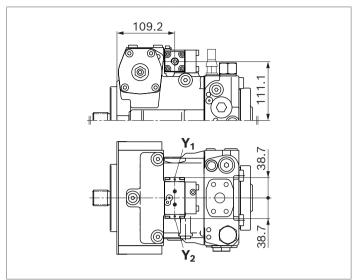
<sup>8)</sup> The countersink can be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E

<sup>9)</sup> Optional, see page 79

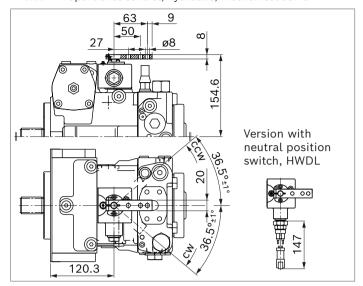
<sup>10)</sup> The diameter of the countersink deviates from the standard. (For details, see page 82, dimensions of the countersinks)

<sup>11)</sup> O = Must be connected (plugged on delivery)X = Plugged (in normal operation)

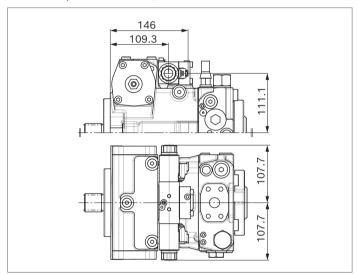
▼ HD - Proportional control, hydraulic, pilot-pressure related



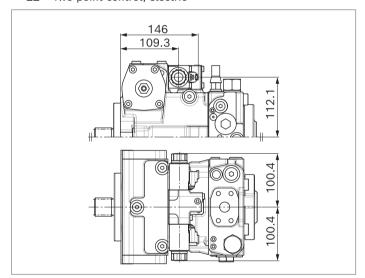
▼ **HW** - Proportional control, hydraulic, mechanical servo



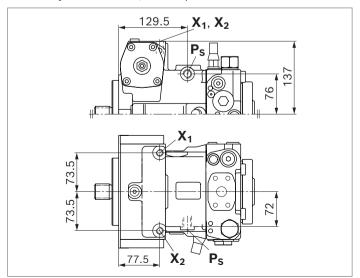
▼ **EP** - Proportional control, electric



▼ **EZ** - Two-point control, electric

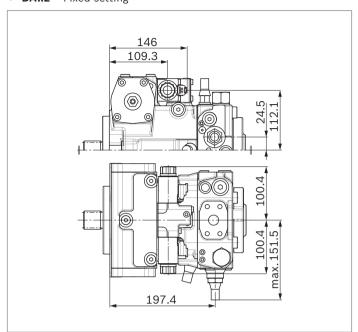


▼ **DG** - Hydraulic control, direct operated

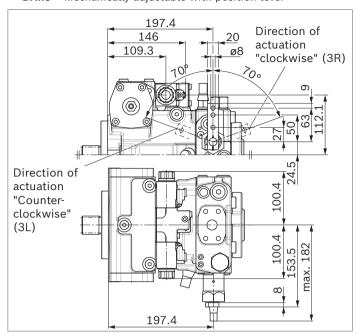


#### **DA** control valve

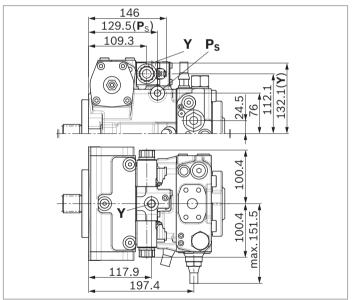
# ▼ DA..2 - Fixed setting



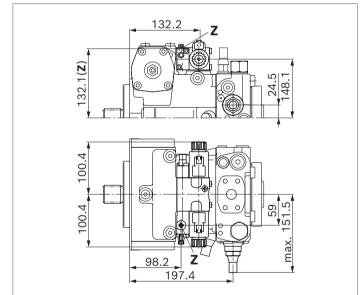
▼ DA..3 - Mechanically adjustable with position lever



▼ DA..7 - Fixed setting and ports for pilot control device



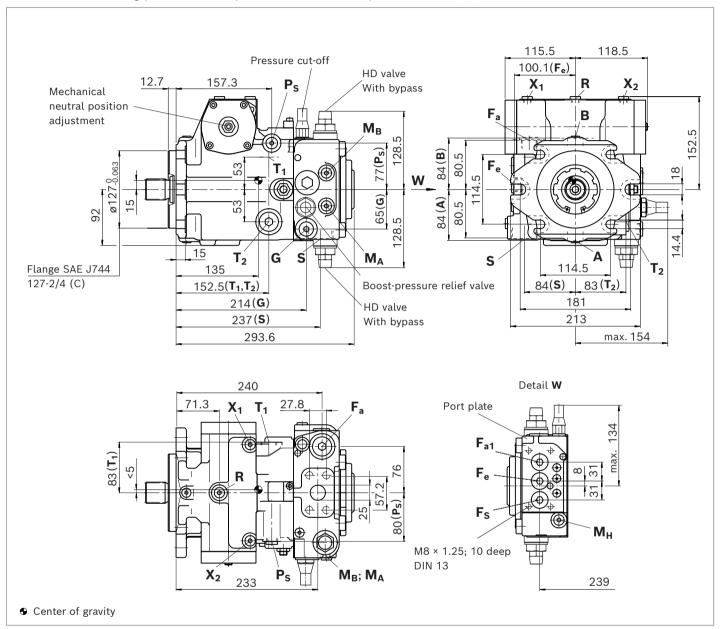
▼ DA..8 - Fixed setting and inch valve mounted



# **Dimensions, size 71**

# **Version without control module**

Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (02)

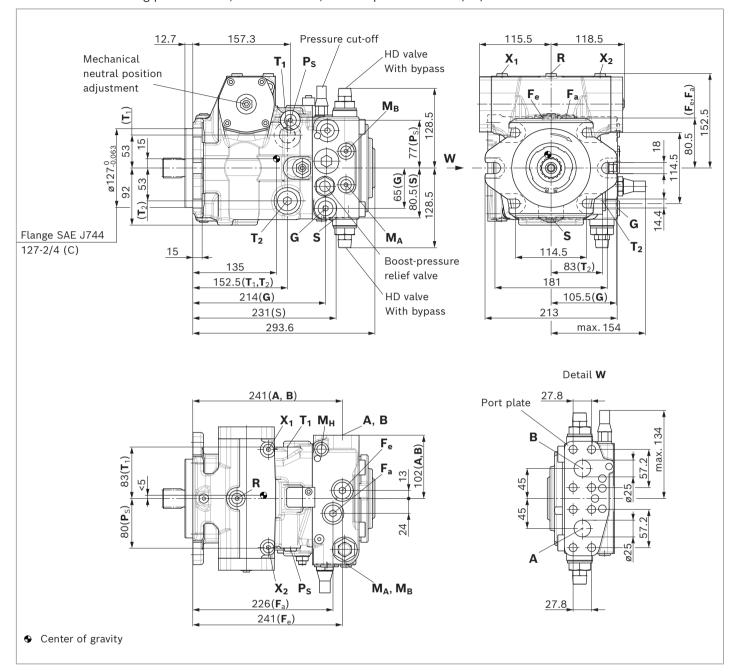


# **Notice**

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (03). Port plate (02) rotated through 180°, installation drawing on request

#### **Version without control module**

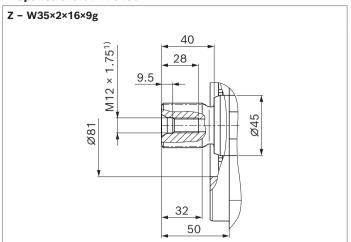
Standard: SAE working port A and B, same side left, suction port S bottom (10)



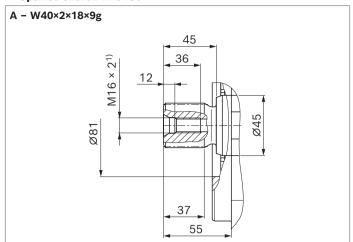
### **Notice**

Option: SAE working port  ${\bf A}$  and  ${\bf B}$ , same side right, suction port  ${\bf S}$  top (13), installation drawing on request

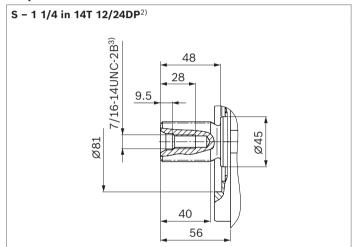
# ▼ Splined shaft DIN 5480



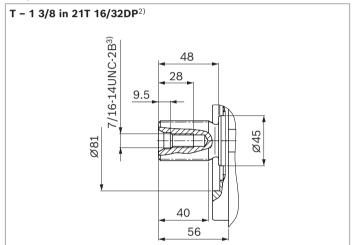
# ▼ Splined shaft DIN 5480



# ▼ Splined shaft ANSI B92.1a



# ▼ Splined shaft ANSI B92.1a



<sup>1)</sup> Center bore according to DIN 332 (thread according to DIN 13)

 $_{\rm 2)}$  Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>3)</sup> Thread according to ASME B1.1

Ports		Standard	Size	$p_{\sf max}$ [bar] $^{4)}$	State <sup>11)</sup>
А, В	Working port	SAEJ518 <sup>5)</sup>	1 in	450	0
	Fastening thread	DIN 13	M12 × 1.75; 17 deep		
S	Suction port	DIN 3852 <sup>8)</sup>	M42 × 2; 20 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	DIN 38528)	M26 × 1.5; 16 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	DIN 38528)	M26 × 1.5; 16 deep	3	X <sup>7)</sup>
R	Air bleed port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	3	Χ
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	DIN 38528)	M12 × 1.5; 12 deep	40	Χ
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice, DG only)	DIN 38528)	M12 × 1.5; 12 deep	40	0
<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub> <sup>9)</sup>	Stroking chamber pressure port	DIN 38528)	M12 × 1.5; 12 deep	40	Χ
G	Boost pressure port inlet	DIN 38528)	M18 × 1.5; 12 deep	40	Χ
Ps	Pilot pressure port	DIN 38528)	M14 × 1.5; 12 deep	40	Χ
Ps	Pilot pressure port (DA7 only)	DIN 38528)	M14 × 1.5; 12 deep	40	0
Υ	Pilot pressure port outlet (only DA7)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
$\mathbf{M}_{A},\mathbf{M}_{B}$	Measuring port pressure A, B	DIN 38528)	M12 × 1.5; 12 deep	450	Χ
M <sub>H</sub>	Measuring port, high pressure	DIN 38528)	M12 × 1.5; 12 deep	450	Χ
<b>F</b> <sub>a</sub>	Boost pressure port inlet	DIN 38528)	M26 × 1.5; 16 deep	40	X
<b>F</b> <sub>a1</sub> <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	Χ
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	Х
<b>F</b> <sub>S</sub> <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	Х
<b>Y</b> <sub>1</sub> , <b>Y</b> <sub>2</sub>	Pilot pressure port (pilot signal HD only)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 8 deep	40	0
Z	Pilot pressure port (inch signal only DA8)	DIN 3852 <sup>8)</sup>	M10 × 1; 12 deep	80	Х

<sup>4)</sup> Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

 $_{5)}$  Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

<sup>6)</sup> Plugged for external boost pressure supply.

<sup>7)</sup> Depending on installation position,  $T_1$  or  $T_2$  must be connected (see also installation instructions on page 89).

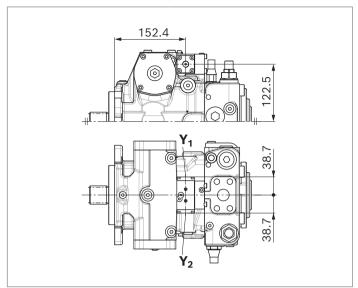
<sup>8)</sup> The countersink can be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E

<sup>9)</sup> Optional, see page 79

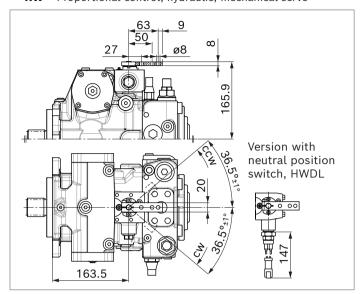
<sup>10)</sup> The diameter of the countersink deviates from the standard. (For details, see page 82, dimensions of the countersinks)

<sup>11)</sup> O = Must be connected (plugged on delivery)
 X = Plugged (in normal operation)

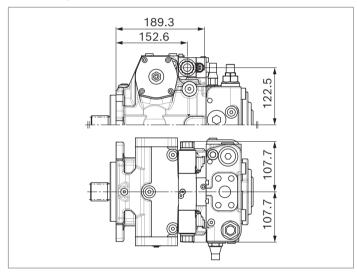
50



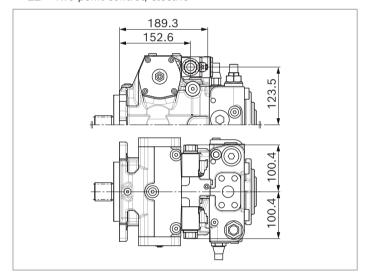
▼ **HW** - Proportional control, hydraulic, mechanical servo



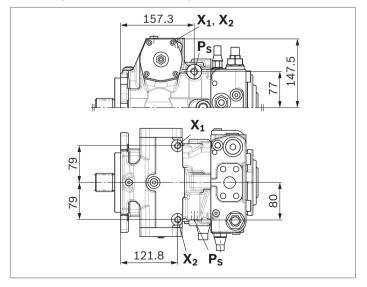
▼ **EP** – Proportional control, electric



▼ **EZ** - Two-point control, electric



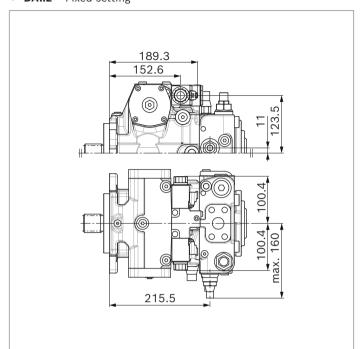
▼ **DG** - Hydraulic control, direct operated



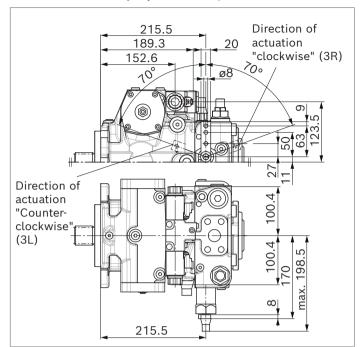
# Dimensions, size 71

#### **DA** control valve

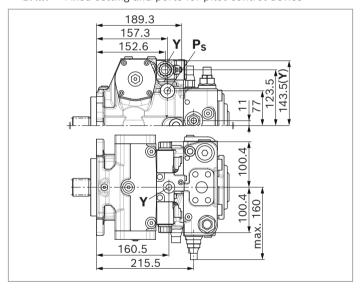
# ▼ DA..2 - Fixed setting



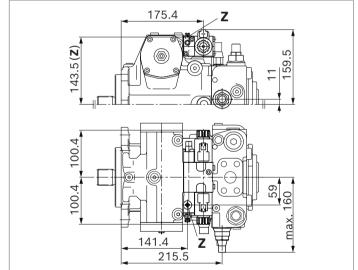
▼ DA..3 - Mechanically adjustable with position lever



▼ DA..7 - Fixed setting and ports for pilot control device



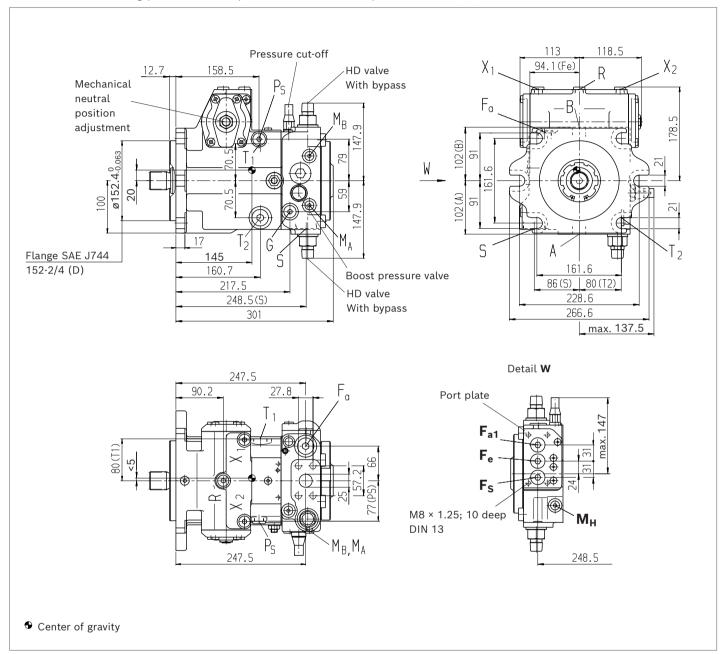
▼ DA..8 - Fixed setting and inch valve mounted



# Dimensions, size 90

# **Version without control module**

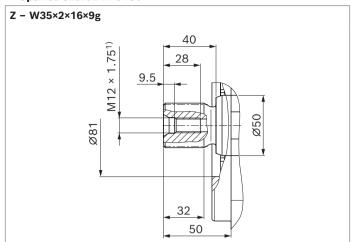
Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (02)



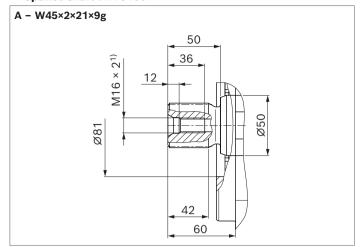
#### **Notice**

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (03). Port plate (02) rotated through 180°, installation drawing on request

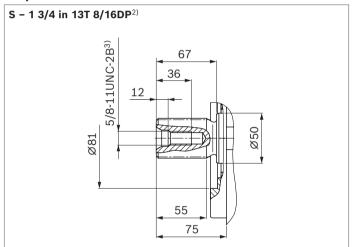
# ▼ Splined shaft DIN 5480



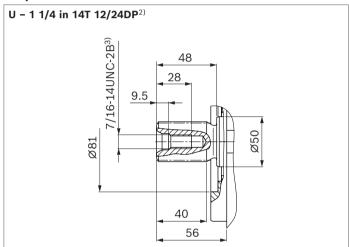
# ▼ Splined shaft DIN 5480



# ▼ Splined shaft ANSI B92.1a



# ▼ Splined shaft ANSI B92.1a



<sup>1)</sup> Center bore according to DIN 332 (thread according to DIN 13)

 $_{\rm 2)}$  Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>3)</sup> Thread according to ASME B1.1

Ports		Standard	Size	$p_{\sf max}$ [bar] $^{4)}$	State <sup>11)</sup>
A, B	Working port Fastening thread	SAEJ518 <sup>5)</sup> DIN 13	1 in M12 × 1.75; 17 deep	450	0
s	Suction port	DIN 3852 <sup>8)</sup>	M42 × 2; 20 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	DIN 3852 <sup>8)</sup>	M26 × 1.5; 16 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	DIN 3852 <sup>8)</sup>	M26 × 1.5; 16 deep	3	X <sup>7)</sup>
R	Air bleed port	DIN 3852 <sup>8)</sup>	M16 × 1.5; 12 deep	3	X
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	DIN 3852 <sup>8)</sup>	M16 × 1.5; 12 deep	40	Х
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice, DG only)	DIN 3852 <sup>8)</sup>	M16 × 1.5; 12 deep	40	0
<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub> <sup>9)</sup>	Stroking chamber pressure port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	X
G	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	Х
Ps	Pilot pressure port	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
Ps	Pilot pressure port (DA7 only)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	0
Υ	Pilot pressure port outlet (only DA7)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring port pressure A, B	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	X
M <sub>H</sub>	Measuring port, high pressure	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	X
<b>F</b> a	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M26 × 1.5; 16 deep	40	X
<b>F</b> a1 <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	Х
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	Χ
<b>F</b> s <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	Χ
<b>Y</b> <sub>1</sub> , <b>Y</b> <sub>2</sub>	Pilot pressure port (pilot signal HD only)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
Z	Pilot pressure port (inch signal only DA8)	DIN 3852 <sup>8)</sup>	M10 × 1; 8 deep	80	Х

<sup>4)</sup> Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

 $_{5)}$  Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.

<sup>6)</sup> Plugged for external boost pressure supply.

<sup>7)</sup> Depending on installation position,  $T_1$  or  $T_2$  must be connected (see also installation instructions on page 89).

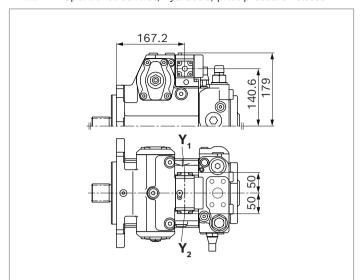
<sup>8)</sup> The countersink can be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E

<sup>9)</sup> Optional, see page 79

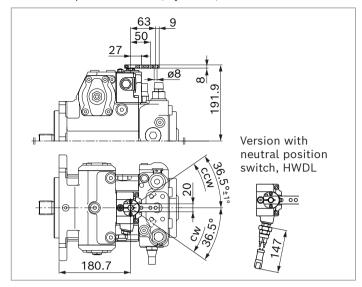
<sup>10)</sup> The diameter of the countersink deviates from the standard. (For details, see page 82, dimensions of the countersinks)

<sup>11)</sup> O = Must be connected (plugged on delivery)X = Plugged (in normal operation)

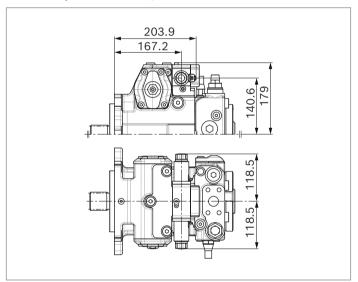
# ▼ HD - Proportional control, hydraulic, pilot-pressure related



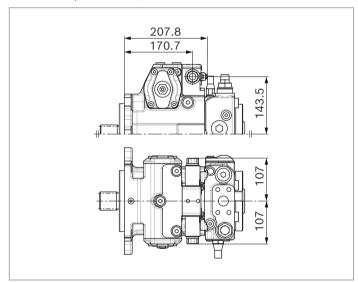
▼ **HW** - Proportional control, hydraulic, mechanical servo



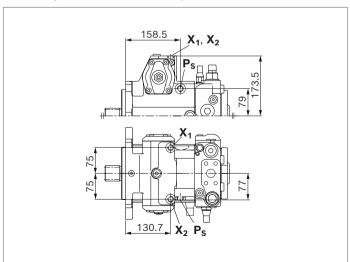
▼ **EP** - Proportional control, electric



▼ **EZ** - Two-point control, electric

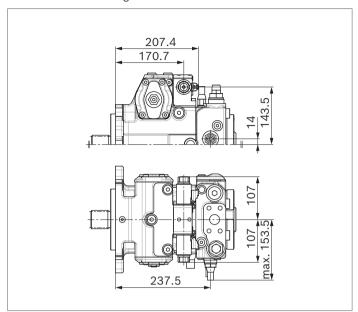


▼ **DG** - Hydraulic control, direct operated

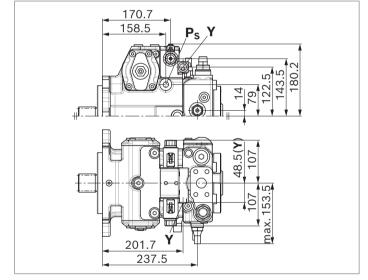


#### **DA** control valve

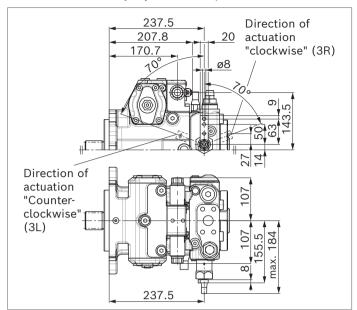
# ▼ DA..2 - Fixed setting



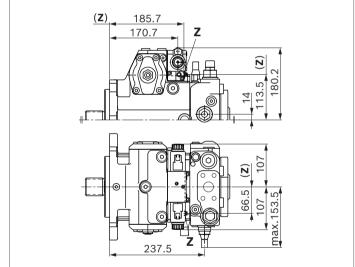
▼ DA..7 - Fixed setting and ports for pilot control device



▼ DA..3 - Mechanically adjustable with position lever



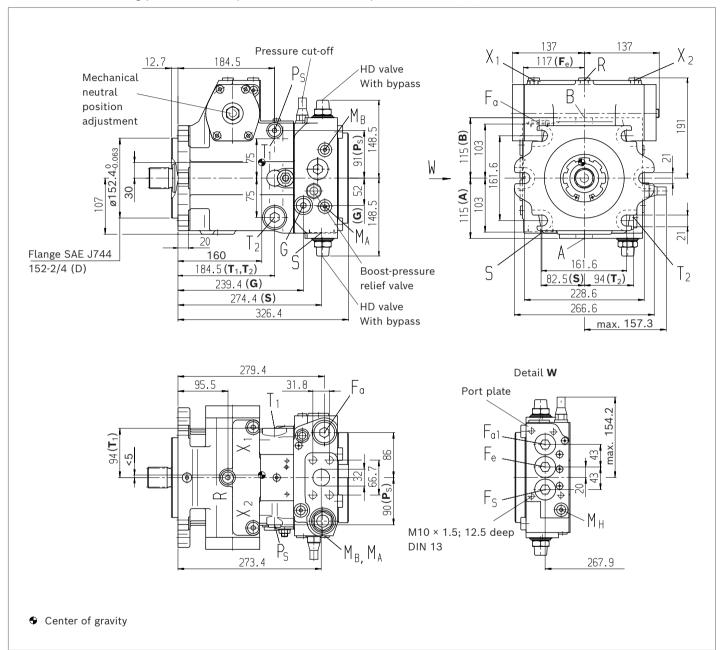
▼ DA..8 - Fixed setting and inch valve mounted



# **Dimensions, size 125**

# **Version without control module**

Standard: SAE working port **A** and **B** top and bottom, suction port **S** bottom (02)

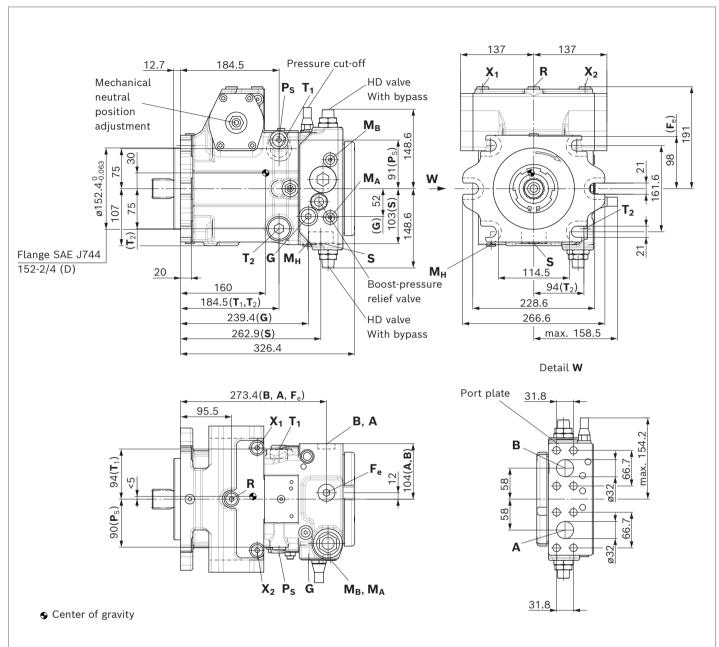


#### **Notice**

Option: SAE working port **A** and **B** top and bottom, suction port **S** top (03). Port plate (02) rotated through 180°, installation drawing on request

#### **Version without control module**

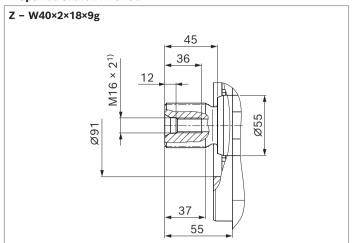
Standard: SAE working port A and B, same side left, suction port S bottom (10)



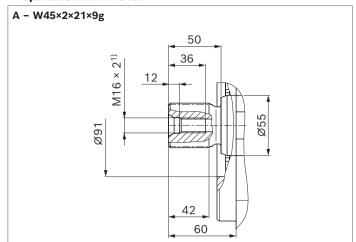
#### **Notice**

Option: SAE working port **A** and **B**, same side right, suction port **S** top (13), installation drawing on request

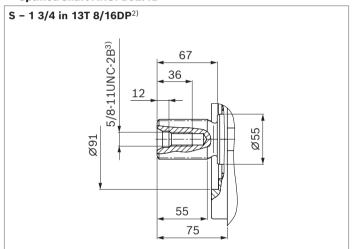
# ▼ Splined shaft DIN 5480



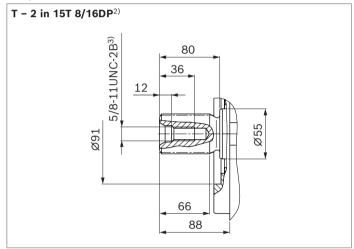
# ▼ Splined shaft DIN 5480



# ▼ Splined shaft ANSI B92.1a



# ▼ Splined shaft ANSI B92.1a



<sup>1)</sup> Center bore according to DIN 332 (thread according to DIN 13)

 $_{\rm 2)}$  Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>3)</sup> Thread according to ASME B1.1

#### ▼ Connection table for port plate 02, 03, 10 and 13

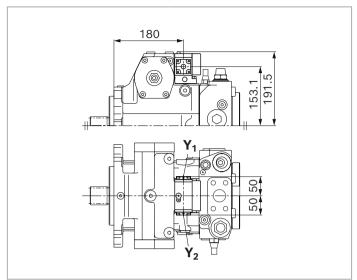
Ports		Standard	Size	$p_{\sf max}$ [bar] $^{4)}$	State <sup>12)</sup>
A, B	Working port	SAEJ518 <sup>5)</sup>	1 1/4 in	450	0
	Fastening thread	DIN 13	M14 × 2; 19 deep		
S	Suction port	DIN 3852 <sup>8)</sup>	M48 × 2; 22 deep	5	O <sup>6)</sup>
<b>T</b> <sub>1</sub>	Drain port	DIN 38528)	M33 × 2; 18 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	3	X <sup>7)</sup>
R	Air bleed port	DIN 3852 <sup>8)</sup>	M16 × 1.5; 12 deep	3	Х
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	DIN 3852 <sup>8)</sup>	M16 × 1.5; 12 deep	40	Χ
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice, DG only)	DIN 3852 <sup>8)</sup>	M16 × 1.5; 12 deep	40	0
<b>X</b> <sub>3</sub> , <b>X</b> <sub>4</sub> <sup>9)</sup>	Stroking chamber pressure port	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	40	X
G	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M22 × 1.5; 14 deep	40	X
Ps	Pilot pressure port	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	X
Ps	Pilot pressure port (DA7 only)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	0
Υ	Pilot pressure port outlet (only DA7)	DIN 3852 <sup>8)</sup>	M18 × 1.5; 12 deep	40	0
<b>M</b> <sub>A</sub> , <b>M</b> <sub>B</sub>	Measuring port pressure A, B	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	X
M <sub>H</sub>	Measuring port, high pressure	DIN 3852 <sup>8)</sup>	M12 × 1.5; 12 deep	450	Х
<b>F</b> <sub>a</sub>	Boost pressure port inlet	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	Х
<b>F</b> <sub>a1</sub> <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	Χ
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	X
<b>F</b> s <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	Х
<b>Y</b> <sub>1</sub> , <b>Y</b> <sub>2</sub>	Pilot pressure port (pilot signal HD only)	DIN 3852 <sup>8)</sup>	M14 × 1.5; 12 deep	40	0
Z	Pilot pressure port (inch signal only DA8)	DIN 3852 <sup>8)</sup>	M10 × 1; 8 deep	80	X

#### ▼ Connection table for port plate 22

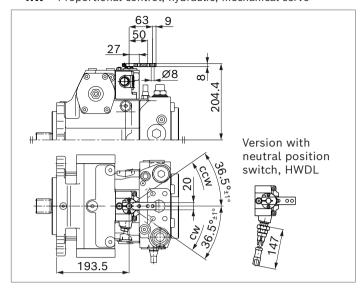
Ports		Standard	Size	$p_{max}$ [bar] $^{4)}$	State <sup>12)</sup>
A, B	Working port	SAEJ518 <sup>5)</sup>	1 1/4 in	450	0
	Fastening thread	DIN 13	M14 × 2; 19 deep		
S	Suction port	ISO 6149 <sup>11)</sup>	M48 × 2; 22 deep	5	O <sub>6</sub> )
<b>T</b> <sub>1</sub>	Drain port	ISO 6149 <sup>11)</sup>	M33 × 2; 19 deep	3	O <sup>7)</sup>
<b>T</b> <sub>2</sub>	Drain port	ISO 6149 <sup>11)</sup>	M33 × 2; 19 deep	3	X <sup>7)</sup>
R	Air bleed port	ISO 6149 <sup>11)</sup>	M14 × 1.5; 11.5 deep	3	Х
<b>X</b> <sub>1</sub> , <b>X</b> <sub>2</sub>	Control pressure port (upstream of orifice)	ISO 6149 <sup>11)</sup>	M14 × 1.5; 11.5 deep	40	Х
G	Boost pressure port inlet	ISO 6149 <sup>11)</sup>	M22 × 1.5; 15.5 deep	40	Х
Ps	Pilot pressure port	ISO 6149 <sup>11)</sup>	M18 × 1.5; 14.5 deep	40	Х
M <sub>A</sub> , M <sub>B</sub>	Measuring port pressure A, B	ISO 6149 <sup>11)</sup>	M14 × 1.5; 12 deep	450	Х
<b>F</b> a	Boost pressure port inlet	ISO 6149 <sup>11)</sup>	M33 × 2; 19 deep	40	Х
<b>F</b> <sub>a1</sub> <sup>10)</sup>	Boost pressure port inlet (attachment filter)	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	Х
<b>F</b> <sub>e</sub> <sup>10)</sup>	Boost pressure port outlet	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	Х
<b>F</b> s <sup>10)</sup>	Line from filter to suction port (cold start)	DIN 3852 <sup>8)</sup>	M33 × 2; 18 deep	40	Χ

- 4) Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.
- 5) Only dimensions according to SAE J518, metric fastening thread is a deviation from the standard.
- 6) Plugged for external boost pressure supply.
- 7) Depending on installation position,  $T_1$  or  $T_2$  must be connected (see also installation instructions on page 89).
- 8) The countersink can be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E
- 9) Optional, see page 79
- 10) The diameter of the countersink deviates from the standard. (For details, see page 82, dimensions of the countersinks)
- 11) The countersink may be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 6149-2
- 12) O = Must be connected (plugged on delivery)
- X = Plugged (in normal operation)

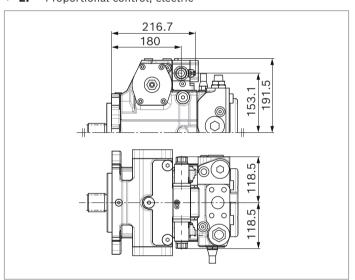
# ▼ HD - Proportional control, hydraulic, pilot-pressure related



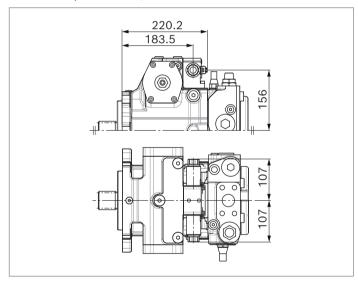
▼ **HW** - Proportional control, hydraulic, mechanical servo



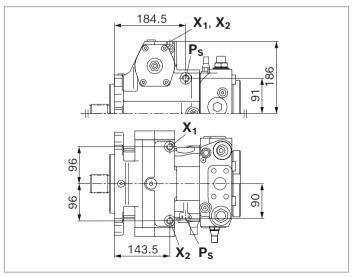
▼ **EP** - Proportional control, electric



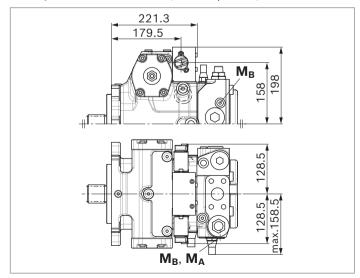
▼ **EZ** - Two-point control, electric



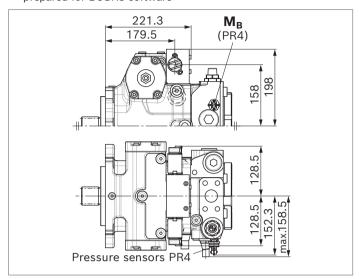
▼ **DG** - Hydraulic control, direct operated



▼ ET7/ET8 - Electronic control, direct operated, two DRE5



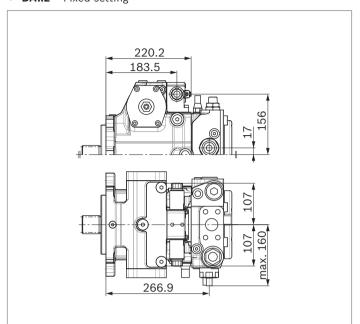
▼ ETA/ETB – Electronic control, direct operated, prepared for BODAS software



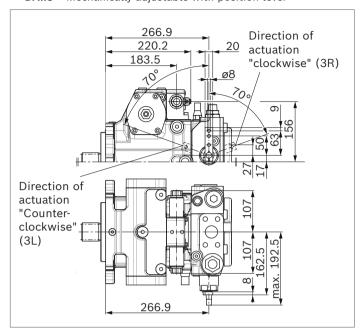
### Dimensions, size 125

#### **DA** control valve

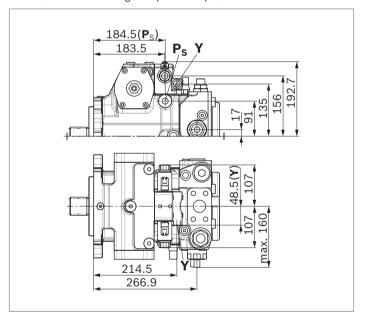
# ▼ DA..2 - Fixed setting



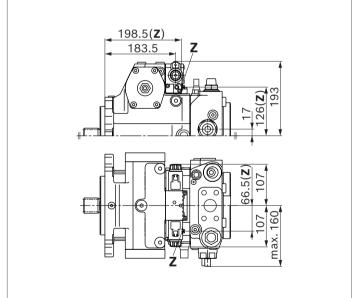
▼ DA..3 - Mechanically adjustable with position lever



▼ DA..7 - Fixed setting and ports for pilot control device



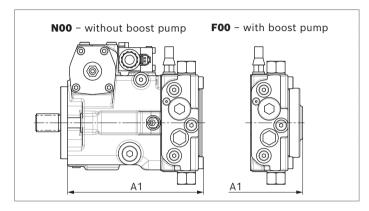
▼ DA..8 - Fixed setting and inch valve mounted



# **Dimensions, through drive**

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
Without through drive		•	•	•	•	•	•	00
82-2 (A)	5/8 in 9T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	01

#### ▼ N00 (without boost pump, without through drive) / F00 (with boost pump, without through drive)

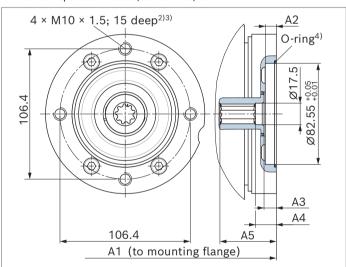


NG	A1 (N00)	A1 (F00)	
28	213.9	223.4	
40	220.2	235.7	
56	239.4	256.4	
71	279.1	293.6	
90	287	301	
125	320.9	326.4	

# ▼ F01<sup>5)</sup>, sizes 28 to 71 (with boost pump)

Flange SAE J744: 82-2 (A)

Hub for splined shaft: 5/8 in 9T 16/32DP1)

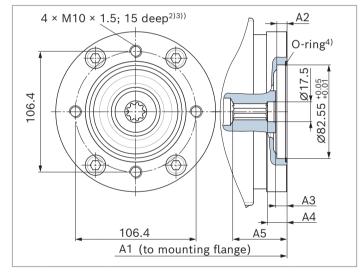


NG	A1	A2	А3	A4	A5
28	227.9	7.5	8.2	15.2	33.9
40	239.7	9	10	17	46
56	261.4	10	11	18	38.3
71	297.6	9	10	17	47.8

# ▼ K01<sup>5)</sup>, sizes 28 to 71 (without boost pump)

Flange SAE J744: 82-2 (A)

Hub for splined shaft: 5/8 in 9T 16/32DP<sup>1)</sup>



NG	A1	A2	А3	A4	A5
28	227.9	7.5	7.5	-	33.2
40	234.2	7.5	8.5	-	34.5
56	254.9	7.5	9	-	30.3
71	297.6	9	10	17.2	47.8

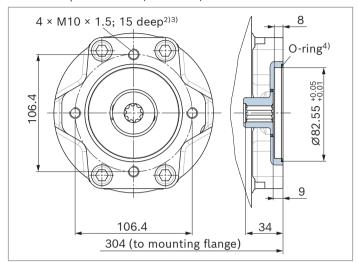
- Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
82-2 (A)	5/8 in 9T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	01

#### ▼ F01<sup>4)</sup>, size 90 (with boost pump)

Flange SAE J744: 82-2 (A)

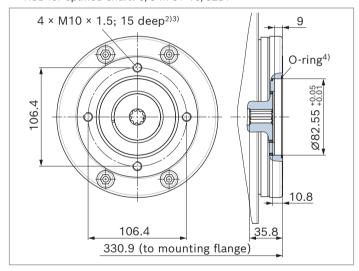
Hub for splined shaft: 5/8 in 9T 16/32DP1)



#### ▼ F01<sup>4)</sup>, size 125 (with boost pump)

Flange SAE J744: 82-2 (A)

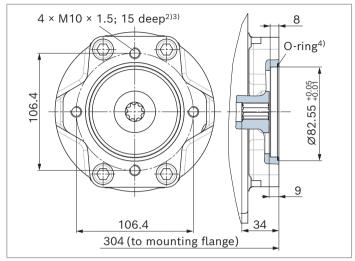
Hub for splined shaft: 5/8 in 9T 16/32DP1)



#### ▼ K01<sup>4)</sup>, size 90 (without boost pump)

Flange SAE J744: 82-2 (A)

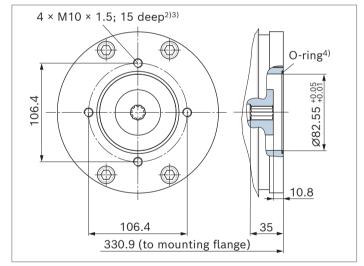
Hub for splined shaft: 5/8 in 9T 16/32DP1)



#### ▼ K01<sup>4)</sup>, size 125 (without boost pump)

Flange SAE J744: 82-2 (A)

Hub for splined shaft: 5/8 in 9T 16/32DP1)



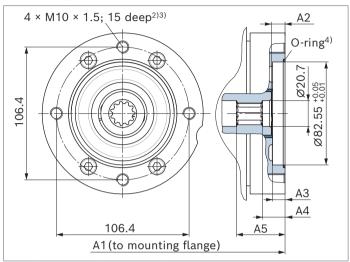
- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
82-2 (A)	3/4 in 11T 16/32DP <sup>1)</sup>	-	•	•	•	-	-	52
101-2 (B)	7/8 in 13T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	02

### **▼ F52**<sup>4)</sup>, sizes 40 to 71 (with boost pump)

Flange SAE J744: 82-2 (A)

Hub for splined shaft: 3/4 in 11T 16/32DP1)

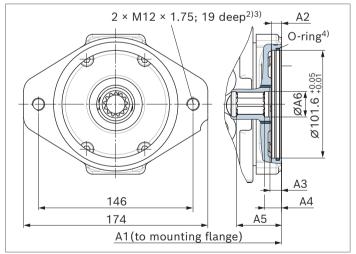


NG	A1	A2	А3	A4	A5
40	239.7	9	10	17	38
56	261.4	10	11	18	39
71	297.6	9	10	17	50

# ▼ F02, sizes 28 to 56 (with boost pump)

Flange SAE J744: 101-2 (B)

Hub for splined shaft: 7/8 in 13T  $16/32DP^{1)}$ 



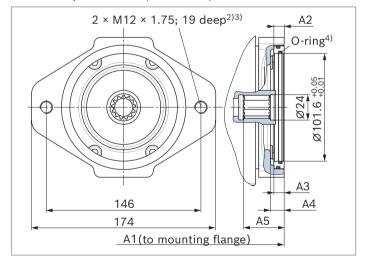
NG	A1	A2	А3	A4	A5	ØA6	
28	230.4	9.7	10.7	16.2	42.3	24	
40	240.7	9.7	11	16	42.6	24	
56	262.4	11	12	18.5	48.4	25	

- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1

### ▼ K02, sizes 28 to 56 (without boost pump)

Flange SAE J744: 101-2 (B)

Hub for splined shaft: 7/8 in 13T 16/32DP1)



NG	A1	A2	А3	A4	A5	
28	230.4	8	9.7	13.5	38.4	
40	240.7	8	9.7	13	38.4	
56	262.4	11	12	20.5	43.4	

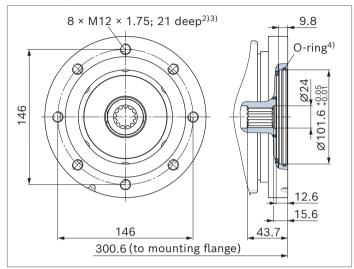
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
101-2 (B)	7/8 in 13T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	02

#### ▼ F02<sup>4)</sup>, size 71 (with boost pump)

Flange SAE J744: 101-2 (B)

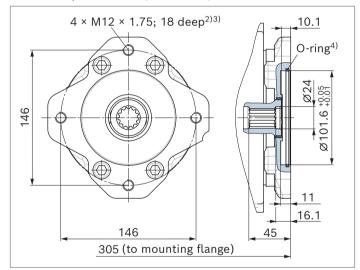
Hub for splined shaft: 7/8 in 13T 16/32DP1)



#### ▼ F02<sup>4)</sup>, size 90 (with boost pump)

Flange SAE J744: 101-2 (B)

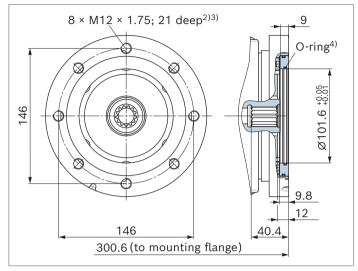
Hub for splined shaft: 7/8 in 13T 16/32DP1)



### ▼ K02<sup>4)</sup>, size 71 (without boost pump)

Flange SAE J744: 101-2 (B)

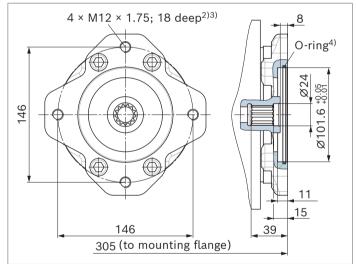
Hub for splined shaft: 7/8 in 13T 16/32DP1)



### ▼ K02<sup>4)</sup>, size 90 (without boost pump)

Flange SAE J744: 101-2 (B)

Hub for splined shaft: 7/8 in 13T 16/32DP1)



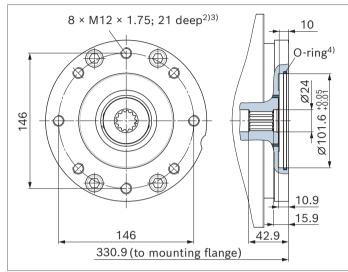
- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
101-2 (B)	7/8 in 13T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	02
	1 in 15T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	04

### ▼ F02<sup>4)</sup>, size 125 (with boost pump)

Flange SAE J744: 101-2 (B)

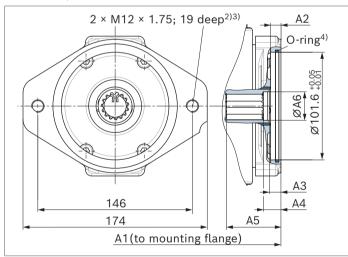
Hub for splined shaft: 7/8 in 13T 16/32DP1)



#### ▼ F04, sizes 28 to 56 (with boost pump)

Flange SAE J744: 101-2 (B)

Hub for splined shaft: 1 in 15T 16/32DP1)



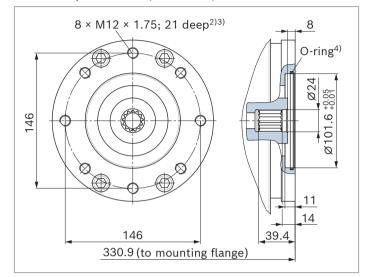
NG	A1	A2	А3	A4	A5	ØA6
28	230.4	9.7	10.7	14.7	42.4	27
40	240.7	9.7	11	16.5	51.6	27
56	262.4	11	12	18	49.1	27

- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

### ▼ K02<sup>4)</sup>, size 125 (without boost pump)

Flange SAE J744: 101-2 (B)

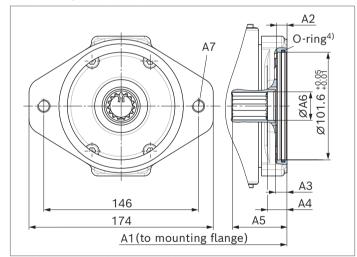
Hub for splined shaft: 7/8 in 13T 16/32DP1)



#### ▼ K04, sizes 28 to 56 (without boost pump)

Flange SAE J744: 101-2 (B)

Hub for splined shaft: 1 in 15T 16/32DP1)



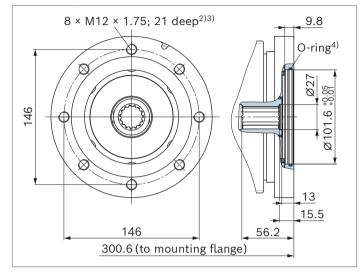
NG	A1	A2	А3	Α4	A5	ØA6	<b>A7</b> <sup>2)3)</sup>
28	230.4	_	10.7	16.2	42.4	-	M12 × 1.75; 19 deep
40	240.7	9.7	11	18.5	51.6	27	M12 × 1.75; 18.7 deep
56	262.4	_	9	17.5	61.7	27	M12 × 1.75; 19 deep

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
101-2 (B)	1 in 15T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	04

#### ▼ F04<sup>4)</sup>, size 71 (with boost pump)

Flange SAE J744: 101-2 (B)

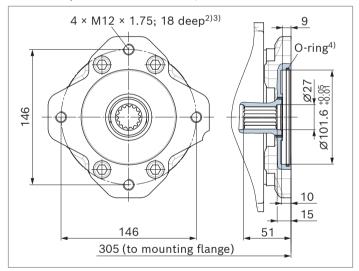
Hub for splined shaft: 1 in 15T 16/32DP1)



# ▼ F04<sup>4)</sup>, size 90 (with boost pump)

Flange SAE J744: 101-2 (B)

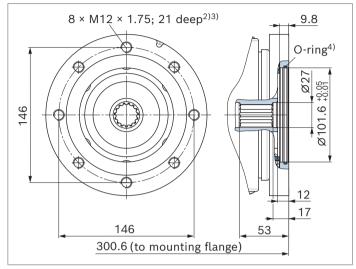
Hub for splined shaft: 1 in 15T 16/32DP<sup>1)</sup>



### ▼ K04<sup>4)</sup>, size 71 (without boost pump)

Flange SAE J744: 101-2 (B)

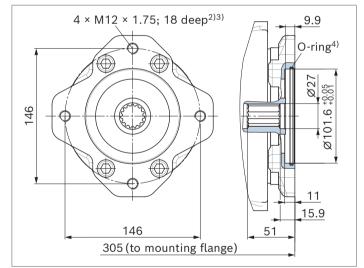
Hub for splined shaft: 1 in 15T 16/32DP<sup>1)</sup>



### ▼ K04<sup>4)</sup>, size 90 (without boost pump)

Flange SAE J744: 101-2 (B)

Hub for splined shaft: 1 in 15T 16/32DP<sup>1)</sup>



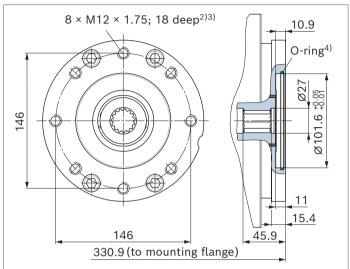
- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
101-2 (B)	1 in 15T 16/32DP <sup>1)</sup>	•	•	•	•	•	•	04
127-2 (C)	1 in 15T 16/32DP <sup>1)</sup>	_	•	-	-	-	-	09

### ▼ F04<sup>4)</sup>, size 125 (with boost pump)

Flange SAE J744: 101-2 (B)

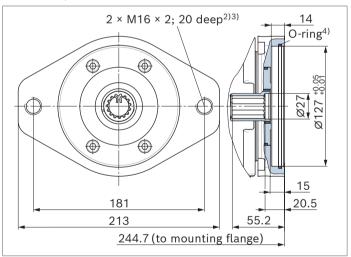
Hub for splined shaft: 1 in 15T 16/32DP1)



#### ▼ F09, size 40 (with boost pump)

Flange SAE J744: 127-2 (C)

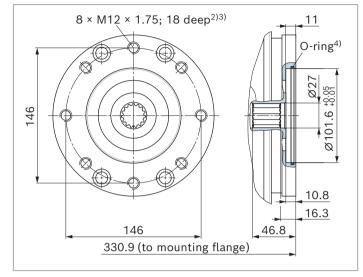
Hub for splined shaft: 1 in 15T 16/32DP1)



# ▼ K04<sup>4)</sup>, size 125 (without boost pump)

Flange SAE J744: 101-2 (B)

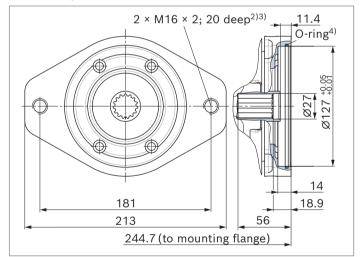
Hub for splined shaft: 1 in 15T 16/32DP1)



#### ▼ K09, size 40 (without boost pump)

Flange SAE J744: 127-2 (C)

Hub for splined shaft: 1 in 15T 16/32DP1)



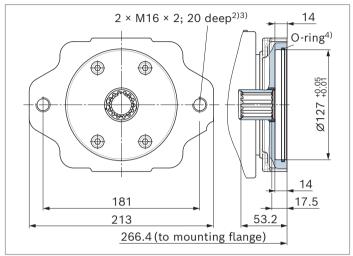
- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
127-2 (C)	1 1/4 in 14T 12/24DP <sup>1)</sup>	-	-	•	•	-	-	0.7
127-2/4 (C)		-	-	-	-	•	•	07

#### ▼ F07<sup>4)</sup>, size 56 (with boost pump)

Flange SAE J744: 127-2 (C)

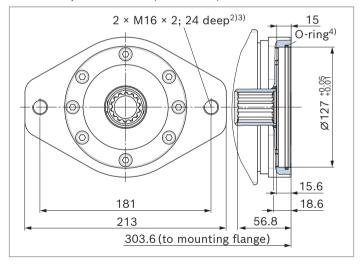
Hub for splined shaft: 1 1/4 in 14T 12/24DP<sup>1)</sup>



#### ▼ F07, size 71 (with boost pump)

Flange SAE J744: 127-2 (C)

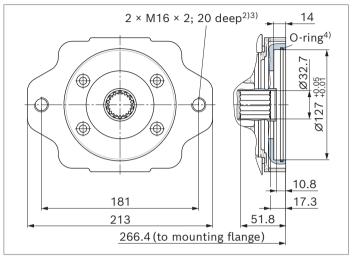
Hub for splined shaft: 1 1/4 in 14T 12/24DP<sup>1)</sup>



### **▼** K07<sup>4)</sup>, size 56 (without boost pump)

Flange SAE J744: 127-2 (C)

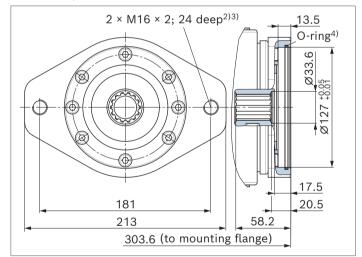
Hub for splined shaft: 1 1/4 in 14T 12/24DP<sup>1)</sup>



#### ▼ K07, size 71 (without boost pump)

Flange SAE J744: 127-2 (C)

Hub for splined shaft: 1 1/4 in 14T 12/24DP1)



<sup>1)</sup> Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>2)</sup> Thread according to DIN 13

 $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1

<sup>4)</sup> O-ring included in the scope of delivery

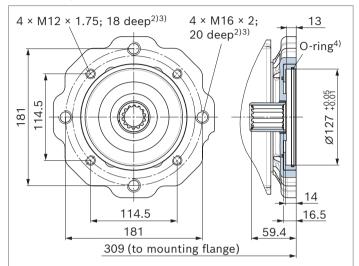
<sup>5)</sup> Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
127-2 (C)	1 1/4 in 14T 12/24DP <sup>1)</sup>	_	-	•	•	-	-	07
127-2/4 (C)		-	_	_	-	•	•	07

### ▼ F07<sup>4)</sup>, size 90 (with boost pump)

Flange SAE J744: 127-2/4 (C)

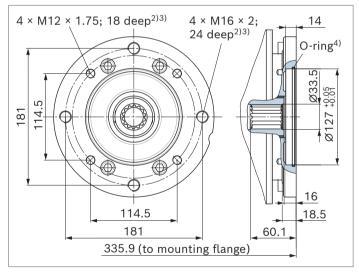
Hub for splined shaft: 1 1/4 in 14T 12/24DP1)



### ▼ F07<sup>4)</sup>, size 125 (with boost pump)

Flange SAE J744: 127-2/4 (C)

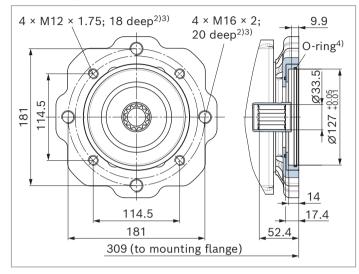
Hub for splined shaft: 1 1/4 in 14T 12/24DP1)



#### ▼ K07<sup>4)</sup>, size 90 (without boost pump)

Flange SAE J744: 127-2/4 (C)

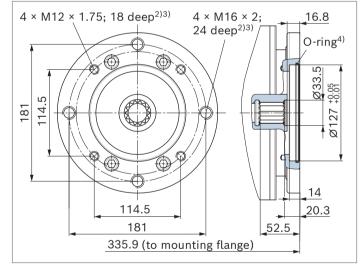
Hub for splined shaft: 1 1/4 in 14T 12/24DP<sup>1)</sup>



#### ▼ K07<sup>4)</sup>, size 125 (without boost pump)

Flange SAE J744: 127-2/4 (C)

Hub for splined shaft: 1 1/4 in 14T 12/24DP1)



<sup>1)</sup> Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

<sup>2)</sup> Thread according to DIN 13

 $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1

<sup>4)</sup> O-ring included in the scope of delivery

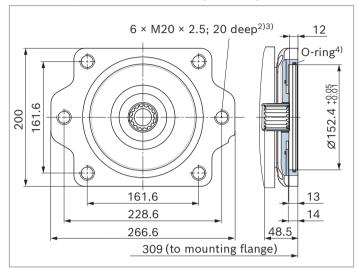
<sup>5)</sup> Please state in plain text whether the 4-hole, the 2-hole horizontal or the 2-hole vertical version is used.

Flange SAE J744	Hub for splined shaft	28	40	56	71	90	125	Code
152-2/4 (D)	W35 2×16×9g (according to DIN 5480)	-	-	-	-	•	-	73
	1 3/4 in 13T 8/16DP <sup>1)</sup>	-	-	-	-	-	•	69

#### ▼ F73<sup>4)</sup>, size 90 (with boost pump)

Flange SAE J744: 152-2/4 (D)

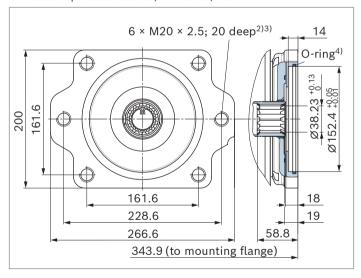
Hub for splined shaft: W35 2×16×9g according to DIN 5480



# ▼ F69<sup>4)</sup>, size 125 (with boost pump)

Flange SAE J744: 152-2/4 (D)

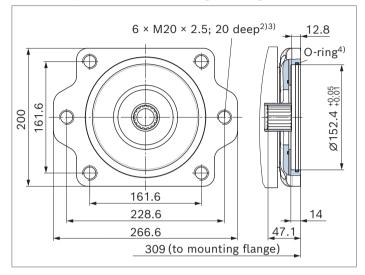
Hub for splined shaft: 1 3/4 in 13T 8/16DP1)



# **▼** K73<sup>4)</sup>, size 90 (without boost pump)

Flange SAE J744: 152-2/4 (D)

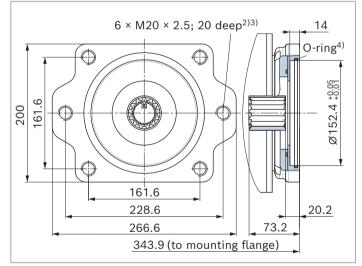
Hub for splined shaft: W35 2×16×9g according to DIN 5480



## ▼ K69<sup>4)</sup>, size 125 (without boost pump)

Flange SAE J744: 152-2/4 (D)

Hub for splined shaft: 1 3/4 in 13T 8/16DP1)



- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13
- $_{3)}$  Design according to VDI 2230 with  $\mu$  = 0.1 for screw quality 8.8 according to ISO 898-1
- 4) O-ring included in the scope of delivery
- 5) Please state in plain text whether the 2-hole, the 4-hole or the 4+2-hole vertical version is used.

# **Overview of mounting options**

Through driv	ve <sup>1)</sup>		Mounting options – 2nd pump			
Flange	Hub for splined shaft	Code	A4VG/32 NG (shaft)	A4VG/35 NG (shaft)	A10VG/10 NG (shaft)	External gear pump <sup>2)</sup>
82-2 (A)	5/8 in	F/K01	-	_	-	AZPF, AZPS NG4 28, AZPW NG5 22
	3/4 in	F52	-	_	-	AZPF NG4 28
101-2 (B)	7/8 in	F/K02	-	_	18 (S)	AZPN-11 NG20 25, AZPG-22 NG28 100
	1 in	F/K04	28 (S)	_	28 (S)	-
					45 (S)	
127-2 (C) <sup>3)</sup>	1 in	F/K09	40 (U)	_	-	-
	1 1/4 in	F/K07	40, 56, 71 (S)	56, 71, 90 (S7)	63 (S)	-
127-4 (C) <sup>3)</sup>	1 in	F/K09	-		-	-
	1 1/4 in	F/K07	71 (S)	71, 90 (S7)	-	-
152-2 (D)	W35	F/K73	90 (Z)	_	-	-
	1 3/4 in	F/K69	90, 125 (S)	_	-	-
152-4 (D)	W35	F/K73	90 (Z)	_	-	-
	1 3/4 in	F/K69	90, 125 (S)	_	-	-

Through drive <sup>1)</sup>			Mounting options – 2nd pump				
Flange	Hub for splined shaft	Code	A10V(S)O/31 NG (shaft)	A10VO/32 NG (shaft)	A10V(S)O/5x NG (shaft)	A11VO/1x NG (shaft)	A1VO/10
82-2 (A)	5/8 in	F/K01	18 (U)	-	10, 18 (U)	_	-
	3/4 in	F52	18 (S)	-	10, 18 (S)	-	18, 28 (S3)
101-2 (B)	7/8 in	F/K02	28 (S) 45 (U)	45 (U)	28 (S) 45 (U)	-	18, 28, 35 (S4)
	1 in	F/K04	45 (S)	45 (S)	45 (S) 60, 63, 72 (U)	40 (S)	35 (S5)
127-2 (C)	1 in	F/K09	71, 88 (U)	71 (U)	-	-	-
	1 1/4 in	F/K07	71, 88 (S) 100 (U)	71 (S) 100 (U)	85, 100 (U)	-	-
127-4 (C) <sup>3)</sup>	1 in	F/K09	-	45 (S) 71 (U)	60, 63, 72 (U)	-	-
	1 1/4 in	F/K07	-	71 (S)	60, 63, 72 (S) 85, 100 (U)	60 (S)	-
152-2 (D)	W35	F/K73	-	-	-	-	-
	1 3/4 in	F/K69	-	-	-	-	-
152-4 (D)	W35	F/K73	-	-	-	-	-
	1 3/4 in	F/K69	140 (S)	140, 180 (S)	-	95, 130, 145 (S)	-

# Notice

The mounting options listed only apply for drive shaft versions with undercut. Please contact us for drive shafts without undercut.

 $_{\mbox{\scriptsize 1)}}$  Availability of the individual sizes, see type code on page 2.

 $<sup>\</sup>ensuremath{\mathtt{2)}}$  Bosch Rexroth recommends special versions of the gear pumps. Please contact us.

 $_{\rm 3)}$  A10VO/5X with 4-hole flange attachable only to A4VG NG90 to 125

# **Combination pumps A4VG + A4VG**

# Total length A

A4VG	A4VG 2nd pump <sup>1)</sup>					
1st pump	NG28	NG40	NG56	NG71	NG90	NG125
NG28	453.8	_	_	_	_	_
NG40	464.1	480.4	_	_	_	_
NG56	485.8	502.1	522.8	_	_	_
NG71	524.0	539.3	560.0	597.2	_	_
NG90	528.4	544.7	565.4	602.6	610.0	_
NG125	554.3	571.6	592.3	629.5	644.9	670.3

By using combination pumps, it is possible to have independent circuits without the need for splitter gearboxes.

When ordering combination pumps the type designations for the 1st and the 2nd pump must be linked by a "+".

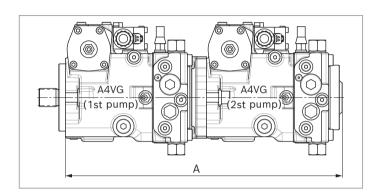
Order example:

# A4VG56EP3D1/32R-NAC02F073SP + A4VG56EP3D1/32R-NSC02F003SP

A tandem pump, with two pumps of equal size, is permissible without additional supports, assuming that the dynamic mass acceleration does not exceed maximum 10 g (= 98.1 m/s<sup>2</sup>).

From size 71 upward, we recommend using the 4-hole mounting flange.

For combination pumps consisting of more than two pumps,-the mounting flange must be rated for the permissible moment of inertia, please contact us.



# Notice

- ► The combination pump type code is shown in shortened form in the order confirmation.
- ► The permissible through-drive torques are to be observed (see page 12).

# **High-pressure relief valves**

The two high-pressure relief valves protect the hydrostatic gear (pump and motor) from overloading. They limit the maximum pressure in the respective high-pressure line and serve simultaneously as boost valves.

The high-pressure relief valves are exclusively intended to protect the system from high-pressure peaks until the control dynamics of the pressure cut-off ensure the intended maximum working pressure.

A hydraulic-mechanical or electronic pressure cut-off must be provided for permanent high pressure limitation.

# **Setting ranges**

High-pressure relief valve, direct operated (NG28 to 56)	Differential pressure setting $\Delta p_{ extsf{HD}}$
Setting range valve <b>3</b> , <b>5</b>	420 bar
$\Delta p_{\rm HD}$ 250 to 420 bar	400 bar
(see type code)	360 bar
	340 bar
	320 bar
	300 bar
	270 bar
	250 bar
Setting range valve <b>4</b> , <b>6</b>	250 bar
$\Delta p_{\text{HD}}$ 100 to 250 bar	230 bar
(see type code)	200 bar
	150 bar
	100 bar

High-pressure relief valve, pilot operated (NG71 to 125)	Differential pressure setting $\Delta p_{\text{HD}}$
Setting range valve 1	420 bar
$\Delta p_{\text{HD}}$ 100 to 420 bar	400 bar
(see type code)	360 bar
	340 bar
	320 bar
	300 bar
	270 bar
	250 bar
	230 bar
	200 bar
	150 bar
	100 bar

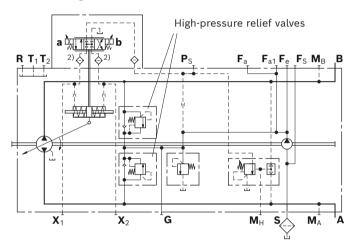
- 1) Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$
- 2) Only sizes 28 to 71 are designed with inlet filtration in  $X_1/X_2$
- 3) Not applicable for version without pressure cut-off.

Settings on high-pressure relief valve A and B					
Differential pressure setting	$\Delta p_{\text{HD}}$ = bar				
Test pressure of the HD valve (at $q_{ m V~1}$ )	p <sub>max</sub> = bar				
$(p_{\text{max}} = \Delta p_{\text{HD}} + p_{\text{Sp}})$					

The valve settings are made at n = 1000 rpm and at  $V_{\rm g\ max}$  ( $q_{\rm v\ 1}$ ). There may be deviations with other operating parameters.

• When ordering, state the differential pressure setting  $\Delta p_{\rm HD}$  in the plain text.

## ▼ Circuit diagram<sup>1)</sup>

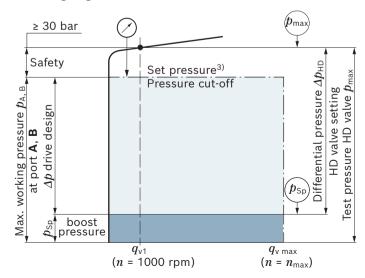


**Example:**  $\Delta p$  drive design = 370 bar  $(p_{A, B} - p_{Sp})$ 

Max. working	-	Boost	+	Safety	=	Differential
pressure $p_{A,B}$	p	ressure p			pressure $\Delta p_{\text{HD}}$	
390 bar	_	20 bar	+	30 bar	=	400 bar

► Test pressure of the HD valve (at  $q_{V1}$ ):  $p_{max} = 420$  bar  $(p_{max} = \Delta p_{HD} + p_{Sp})$ 

# ▼ Setting diagram



Key	
HD valve	High-pressure relief valve
Test pressure HD valve $p_{\max}$	The factory-set pressure value set at $q_{ m V1}$
Differential pressure HD valve $\Delta p_{ ext{HD}}$	Test pressure HD valve (abs.) minus the boost pressure setting
Maximum working pressure $p_{A, B}$	The total design of the hydrostatic drive is based on the maximum working pressure $p_{A, B}$ . It is composed of the feed pressure setting and the $\Delta p$ drive design.
$\Delta p$ Drive design	Differential pressure value determining the available torque at the hydraulic motor ( $p_{A, B} - p_{Sp}$ ).
Boost pressure $p_{Sp}$	Boost pressure setting of the boost-pressure relief valve
Safety	Required distance between maximum working pressure and test pressure of the high-pressure relief valve-to prevent constant response of the high-pressure relief valves at maximum working pressure.

#### **Notice**

Upon response of the high-pressure relief valve, the permissible temperature and viscosity must be complied with.

#### **Bypass function**

A connection between the two high-pressure passages **A** and **B** can be established using the bypass function (e.g. for machine towing).

# ► Towing speed

The maximum towing speed depends on the gear ratio in the vehicle and must be calculated by the vehicle manufacturer. The corresponding flow of  $q_{\rm v}$  = 30 l/min may not be exceeded.

# ► Towing distance

Only tow the vehicle out of the immediate danger zone. For further information on the bypass function, see the instruction manual.

#### **Notice**

The bypass function and the pilot operated high-pressure relief valves (size 71 to 125) are not illustrated in the circuit diagrams.

# **Pressure cut-off**

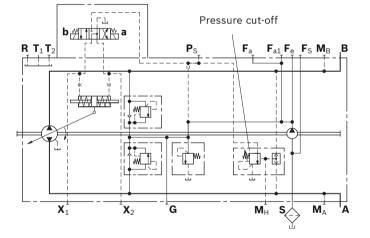
The pressure cut-off is a pressure control which, after reaching the set pressure, adjusts the displacement of the pump back to  $V_{\rm g\ min}$ .

This valve limits the permanent maximum working pressure by reducing the control pressure and thus prevents the high-pressure relief valves from responding. The control dynamics of the pressure cut-off by control pressure reduction depends on the selected control device, rotational speed and operating point of the pump. The system must be designed in such a way that the control dynamics of the pressure cut-off are sufficient to avoid overloading of the high-pressure relief valves. The setting range of the pressure cut-off may be anywhere within the entire working pressure range. However, it must be set 30 bar lower than the setting value of the high-pressure relief valves (see setting diagram, page 76).

The function of the pressure cut-off in combination with a DG control is described on page 20.

Please state the setting value of the pressure cut-off in plain text when ordering.

# ▼ Circuit diagram with pressure cut-off Example: Two-point control, electric, EZ1D/EZ2D



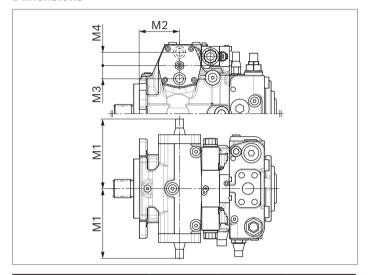
# Mechanical stroke limiter

The mechanical stroke limiter is an auxiliary function allowing the maximum displacement of the pump to be steplessly reduced, regardless of the control module used. By means of two threaded pins, the stroke of the stroking piston and thus the maximum swivel angle of the pump can be limited.

# Notice

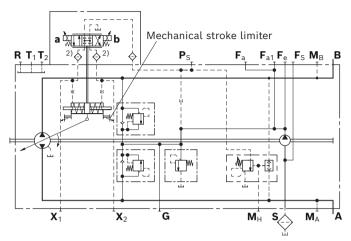
Threaded pins are mounted from the inside (screw-out protection) and can no longer be removed from the outside.

# **Dimensions**



NG	M1 max.	M2	М3	M4
28	125.5	40.1	24	_
40	125.5	38.1	24	_
56	141.5	44	25.5	_
71	151	86.3	-	28.5
90	155	95.7	31.5	_
125	177.5	104.5	-	35.5

# ▼ Circuit diagram<sup>1)</sup>

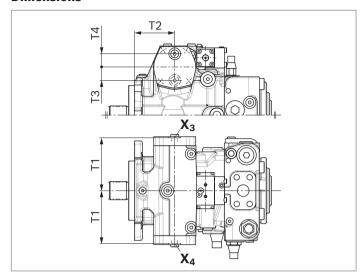


<sup>1)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

 $_{2)}\,$  Only sizes 28 to 71 are designed with inlet filtration in  $\boldsymbol{X}_{1}/\boldsymbol{X}_{2}$ 

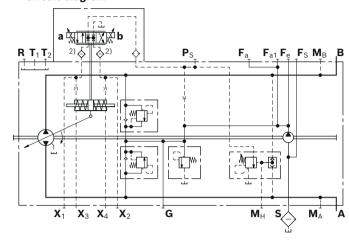
# Stroking chamber pressure port $X_3$ and $X_4$

## **Dimensions**



NG	T1	T2	Т3	T4
28	92	40.1	-	24
40	92	38.1	-	24
56	104.5	44	-	25
71	113.5	86.3	28	-
90	111.5	95.7	-	30
125	136	104.5	34	-

# ▼ Circuit diagram<sup>1)</sup>



Ports		Standard <sup>3)</sup>	Size	$m{p}_{\sf max}$ [bar] $^{4)}$	State <sup>5)</sup>
$X_3, X_4$	Stroking chamber pressure port	DIN 3852	M12 × 1.5; 12 deep	40	Χ

<sup>1)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

 $_{\rm 2)}$  Only sizes 28 to 71 are designed with inlet filtration in  $\boldsymbol{X}_{1}/\boldsymbol{X}_{2}$ 

<sup>3)</sup> The countersink can be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E.

<sup>4)</sup> Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

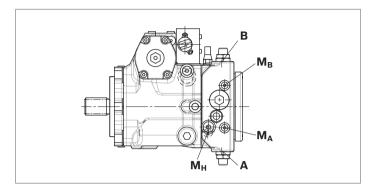
<sup>5)</sup> X = Plugged (in normal operation)

# Measuring ports $M_A$ , $M_B$ , $M_H$

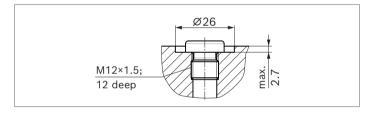
# Working port (port plate) based on DIN 3852

The measuring ports  $\mathbf{M}_{A}$ ,  $\mathbf{M}_{B}$  and  $\mathbf{M}_{H}$  are designed based on DIN 3852 and designed for straight stud ends according to EN ISO 9974-2 type E. The countersink may, however, be deeper than specified in the standard.

## ▼ Porting pattern (example port plate 02)



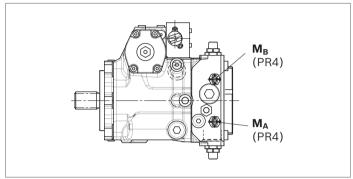
## ▼ Countersink of the measuring ports M<sub>A</sub>, M<sub>B</sub> and M<sub>H</sub>



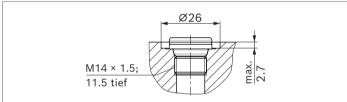
# Working port (port plate) based on ISO 6149

The measuring ports  $\mathbf{M}_{A}$ ,  $\mathbf{M}_{B}$  and are designed based on ISO 6149 and designed for straight stud ends according to EN ISO 6149-2. The countersink may, however, be deeper than specified in the standard.

## ▼ Porting pattern (example port plate 22)



#### ▼ Countersink of the measuring ports M<sub>A</sub>, M<sub>B</sub>



# Filtration in the boost pump suction line

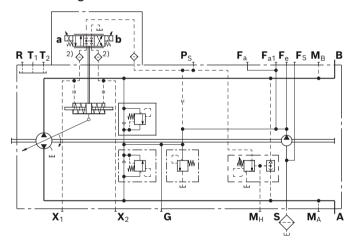
# **Version S**

Filter version	Suction filter		
Recommendation	With contamination indicator,		
	with bypass		
Recommended flow resistance at fi	lter element		
At $v = 30 \text{ mm}^2/\text{s}$ , $n = n_{\text{max}}$	$\Delta p$ = 0.1 bar		
At $v = 1000 \text{ mm}^2/\text{s}$ , $n = n_{\text{max}}$	$\Delta p$ = 0.3 bar		
Pressure at suction port S			
Continuous $p_{\text{S min}}$ ( $v \leq 30 \text{ mm}^2/\text{s}$ )	≥0.8 bar absolute		
Short-term, at a cold start ( $t < 3$	≥ 0.5 bar absolute		
min)			
Maximum pressure $p_{S\ max}$	≤ 5 bar absolute		

Use of version S is preferred.

The suction filter is not included in the scope of delivery.

# ▼ Circuit diagram<sup>1)</sup>



<sup>1)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

 $_{2)}\,$  Only sizes 28 to 71 are designed with inlet filtration in  $\boldsymbol{X}_{1}/\boldsymbol{X}_{2}$ 

# Filtration in the boost pump pressure line

# Version D Ports for external boost circuit filtration

Ports	
Boost pressure inlet	Port <b>F</b> <sub>a</sub>
Boost pressure outlet	Port <b>F</b> <sub>e</sub>
Filter version	Boost pressure filter
Recommendation	With contamination indicator, with cold start valve <sup>3)</sup>
Filter arrangement	Separate in the pressure line (inline filter)

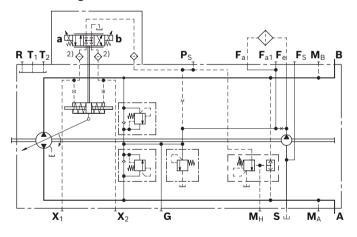
The boost pressure filter is not included in the scope of delivery.

#### **Notice**

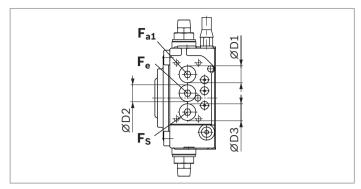
- ► Filters with a bypass are **not recommended**.

  Please contact us for applications with a bypass.
- ▶ On versions with DG control (with pilot pressure not from a boost circuit), a filter must be used that fulfills the requirements with regard to filtration of the hydraulic fluid (see page 7).
- ► The pressure drop at the filter is viscosity- and contamination-dependent. Note the maximum permissible pressure of the boost pump in combination with the set feed pressure.

## ▼ Circuit diagram<sup>1)</sup>



#### **▼** Dimensions of the countersinks F<sub>e</sub>, F<sub>a1</sub>, F<sub>S</sub>



NG	ØD1	ØD2	ØD3
40	24 +0.130	24 +0.130	24 +0.130
56	24 +0.130	24 +0.130	24 +0.130
71	27.5 +0.130	27.5 +0.130	27.5 +0.130
90	27.5 +0.130	27.5 +0.130	27.5 +0.130
125	40 +0.160	40 +0.160	40 +0.160

<sup>1)</sup> Size 28 without port  $\boldsymbol{F}_{a1}$  and  $\boldsymbol{F}_{S}$ 

 $_{2)}\,$  Only sizes 28 to 71 are designed with inlet filtration in  $\boldsymbol{X}_{1}/\boldsymbol{X}_{2}$ 

 $_{\rm 3)}$  Sizes 40 to 125, external piping of cold start valve via port  $\textbf{F}_{\rm S}$  required

# **Version F**<sup>1)</sup> Attachment filter with cold start valve

Filter version	Attachment filter
Recommendation	Version with contamination
	indicator, see P, B
	(differential pressure $\Delta p$ = 5 bar)
Filter grade (absolute)	20 μm
Filter material	Glass fiber
Pressure rating	100 bar
Filter arrangement	Mounted on pump

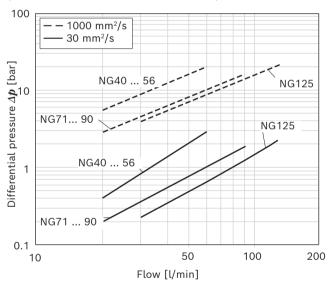
The attachment filter is equipped with a cold start valve and thereby protects the pump from damage. The valve opens at flow resistance of  $\Delta p \ge 6$  bar.

#### **Notice**

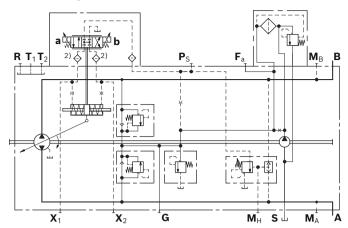
The pressure drop at the filter is viscosity- and contamination-dependent. Note the maximum permissible pressure of the boost pump in combination with the set feed pressure.

#### ▼ Filter characteristic curve

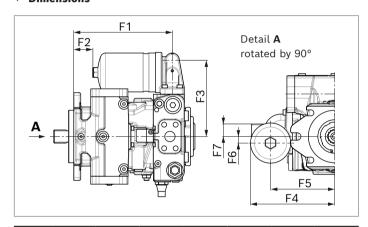
Differential pressure/flow behavior according to ISO 3968 (valid for non-contaminated filter element).



#### ▼ Circuit diagram



#### **▼** Dimensions



NG	F1	F2	F3	F4	F5	F6	F7
40	201.7	47.7	160	175	135	0	42
56	218.4	64.4	163	178	138	0	42
71	239	46.5	185	203.5	155	16	29
90	248.5	56	179	197.5	149	0	45
125	235.9	59.4	201	219.5	171	0	53

To protect the filter element against electrostatic charge buildup, the hydraulic fluid must have a minimum conductivity of 300 pS/m on versions with attachment filter F, P and B. Please contact us if this value cannot be observed.

<sup>2)</sup> Only sizes 40 to 71 are designed with inlet filtration in  $\mathbf{X}_1/\mathbf{X}_2$ 

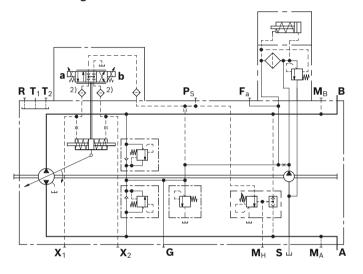
# Version P1)

# Attachment filter with cold start valve and visual contamination indicator

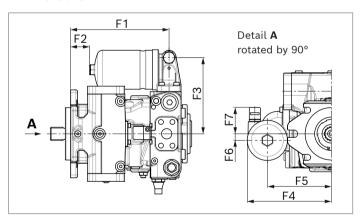
Filtration similar to version F, however with additional visual contamination indicator.

Technical data	
Display type	Green/red window
Differential pressure	$\Delta p$ = 5 bar
(switching pressure)	

#### ▼ Circuit diagram



## **▼** Dimensions



NG	F1	F2	F3	F4	F5	F6	F7
40	201.7	47.7	160	175	135	0	78.5
56	218.4	64.4	163	178	138	0	78.5
71	239	46.5	185	203.5	155	16	65.5
90	248.5	56	179	197.5	149	0	81.5
125	235.9	59.4	201	219.5	171	0	89.5

<sup>1)</sup> To protect the filter element against electrostatic charge buildup, the hydraulic fluid must have a minimum conductivity of 300 pS/m on versions with attachment filter F, P and B. Please contact us if this value cannot be observed.

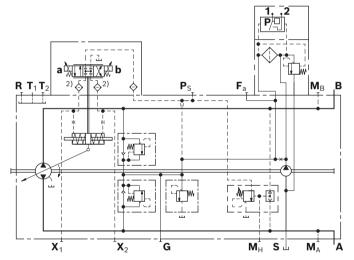
# Version B<sup>1)</sup>

# Attachment filter with cold start valve and electric contamination indicator

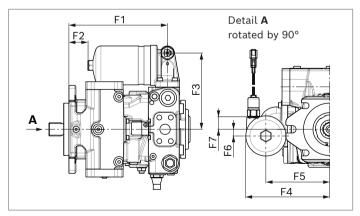
Filtration similar to version F, however with additional electric contamination indicator.

Technical data		
Display type	Electric	
Connector version (mating connector, see page 86)	DEUTSCH DT04-2P-EP04	
Differential pressure (switching pressure)	$\Delta p$ = 5 bar	
Maximum switching capacity	12 V DC 24 W	
	24 V DC 48 W	
Type of protection IP67	DIN/EN 60529	

# ▼ Circuit diagram



## **▼** Dimensions



NG	F1	F2	F3	F4	F5	F6	F7
40	201.7	47.7	160	175	135	0	42
56	218.4	64.4	163	178	138	0	42
71	239	46.5	185	203.5	155	16	29
90	248.5	56	179	197.5	149	0	45
125	235.9	59.4	201	219.5	171	0	53

<sup>2)</sup> Only sizes 40 to 71 are designed with inlet filtration in  $\mathbf{X}_1/\mathbf{X}_2$ 

# **External boost pressure supply**

## Version E

This variation should be used in versions without integrated boost pump (N and/or K).

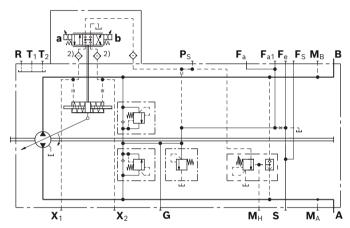
Port **S** is plugged.

The boost pressure supply comes from port  $\mathbf{F}_a$ .

The filter should be installed separately on port  $\mathbf{F}_a$  before the boost pressure supply.

To ensure the functional reliability, maintain the required cleanliness level for the boost fluid fed in at port  ${\bf F}_a$  (see page 7).

# ▼ Circuit diagram<sup>1)</sup>



<sup>1)</sup> Size 28 without port  $\mathbf{F}_{a1}$  and  $\mathbf{F}_{S}$ 

 $_{2)}\,$  Only sizes 28 to 71 are designed with inlet filtration in  $\boldsymbol{X}_{1}/\boldsymbol{X}_{2}$ 

#### **Connector for solenoids**

#### **DEUTSCH DT04-2P-EP04**

- ▶ **P**: Molded, 2-pin, without bidirectional suppressor diode (standard).
- ► **Q**: Molded, 2-pin, with bidirectional suppressor diode (only for switching solenoids on control module EZ and DA)

The following type of protection ensues with the installed mating connector:

- ► IP67 (DIN/EN 60529) and
- ► IP69K (DIN 40050-9)

The protection circuit with bidirectional suppressor diode is needed to limit overvoltages. Overvoltages are caused by switching off the current with switches, relay contacts or by diskonnecting the mating connector while voltage is applied.

## **▼** Switching symbol

**Without** bidirectional suppressor **With** bidirectional suppressor diode



# ▼ Mating connector DEUTSCH DT06-2S-EP04

Consisting of	DT designation
1 housing	DT06-2S-EP04
1 wedge	W2S
2 sockets	0462-201-16141

The mating connector is not included in the scope of delivery. This can be supplied by Bosch Rexroth on request (material number R902601804).

# **Notice**

- ► If necessary, you can change the position of the connector by turning the solenoid.
- ▶ The procedure is defined in the instruction manual.

# **Rotary inch valve**

The rotary inch valve allows for any reduction of pilot pressure, independently of drive speed, through mechanical actuation of the control lever. The control lever is equipped with an internal rotational limiter ±90° (drawing item 1 and 2).

The valve is arranged separately from the pump and is connected to the pump by a hydraulic control line via port  $P_S$  (maximum line length: approx. 2 m).

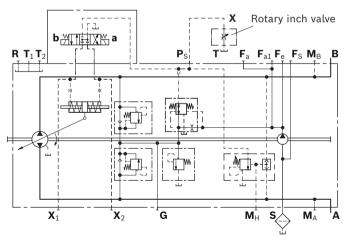
The rotary inch valve must be ordered separately.

NG	Material number	Direction of actuation of the control lever	Throttle cross- section Ø
28, 40,	R902048734	Clockwise	4.6
56, 71, 90	R902048735	Counter-clockwise	4.6
	R902070172	Clockwise	2.7
	R902066994	Counter-clockwise	2.7
125	R902048740	Clockwise	4.7
	R902048741	Counter-clockwise	4.7

#### **Notice**

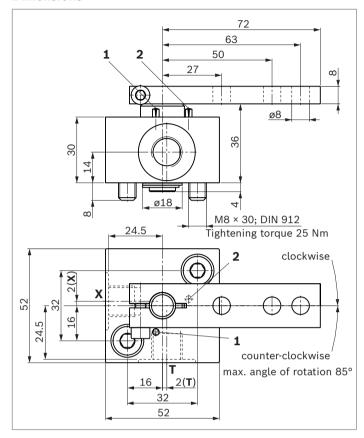
The rotary inch valve can be used regardless of the control module. If necessary, the position of the control lever can be changed.

# ▼ Circuit diagram Hydraulic control, speed related DA with separately attached rotary inch valve



# The countersink may be deeper than specified in the standard. Ports designed for straight stud ends according to EN ISO 9974-2 type E.

#### **Dimensions**



#### **Notice**

To prevent damage to the rotary inch valve, a positive mechanical stop of  $\pm 85^{\circ}$  must be provided for the control lever on the customer side.

Ро	rts	Standard <sup>1)</sup>	Size	<b>p</b> <sub>max</sub> [bar] <sup>2)</sup>	State <sup>3)</sup>
Х	Pilot pressure port	DIN 3852	M14 x 1.5; 12 deep	40	0
Т	Drain port	DIN 3852	M14 x 1.5; 12 deep	3	0

<sup>2)</sup> Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

<sup>3)</sup> O = Must be connected (plugged on delivery)

# Installation dimensions for coupling assembly

To ensure that rotating components (coupling hub) and fixed components (housing, retaining ring) do not come into contact with each other, the installation conditions described here must be observed. This depends on the pump size and the splined shaft.

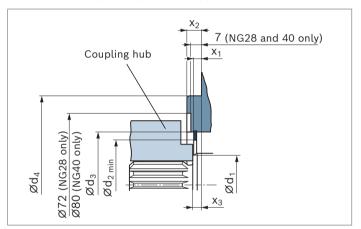
# SAE splined shaft (spline according to ANSI B92.1a)

Splined shaft S and/or T

The outer diameter of the coupling hub must be smaller than the inner diameter of the retaining ring (dimension  $d_2$ ) in the area near the drive shaft collar

(dimension  $x_2 - x_3$ ).

Observe diameter of relief on sizes 28 and 40.

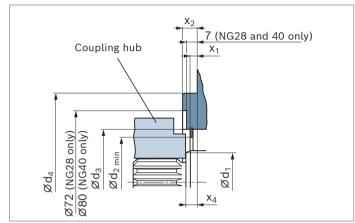


# DIN splined shaft (spline according to DIN 5480)

Splined shaft **Z** or **A** 

The outer diameter of the coupling hub must be smaller than the case diameter  $d_3$  in the area near the drive shaft collar (dimension  $x_2 - x_4$ ).

Observe diameter of relief on sizes 28 and 40.



NG	Ød₁ SAE splined shaft	Ød₁ DIN splined shaft	Ød <sub>2 min</sub>	Ød <sub>3</sub>	$\mathbf{Ød}_4$	<b>x</b> <sub>1</sub>	<b>x</b> <sub>2</sub>	<b>x</b> <sub>3</sub>	<b>x</b> <sub>4</sub>
28	33.5	32.1	43.4	55±0.1	101.6 0 -0.054	3.3+0.2	9.5-0.5	8 +0.9 -0.6	10 +0.9 -0.6
40	38.5	37.1	51.4	63±0.1	127 0 -0.063	4.3+0.2	12.7-0.5	8 +0.9 -0.6	10 +0.9 -0.6
56	38.5	37.1	54.4	68±0.1	127 0 -0.063	7.0+0.2	12.7-0.5	8 +0.9 -0.6	10 +0.9 -0.6
71	43.5	42.1	66.5	81±0.1	127 0 -0.063	7.0+0.2	12.7-0.5	8 +0.9 -0.6	10 +0.9 -0.6
90	48.5	47.1	66.5	81±0.1	152.4 0 -0.063	6.8+0.2	12.7-0.5	8 +0.9 -0.6	10 +0.9 -0.6
125	53.5	52.1	76.3	91±0.1	152.4 0 -0.063	7.0+0.2	12.7-0.5	8 +0.9 -0.6	10 +0.9 -0.6

# **Installation instructions**

#### General

air bled during commissioning and operation. This must also be observed following a longer standstill as the axial piston unit may empty via the hydraulic lines. Particularly in the installation position "drive shaft upwards", filling and air bleeding must be carried out completely as there is, for example, a danger of dry running. The leakage in the housing area must be directed to the reservoir via the highest drain port  $(\mathbf{T}_1, \mathbf{T}_2)$ . For combination pumps, the leakage must be drained off at each single

The axial piston unit must be filled with hydraulic fluid and

If a shared drain line is used for several units, make sure that the respective case pressure in each unit is not exceeded. The shared drain line must be dimensioned to ensure that the maximum permissible case pressure of all connected units is not exceeded in any operating condition, particularly at cold start. If this is not possible, separate drain lines must be laid.

To prevent the transmission of structure-borne noise, use elastic elements to decouple all connecting lines from all vibration-capable components (e.g. reservoir, frame parts).

Under all operating conditions, the suction line and drain line must flow into the reservoir below the minimum fluid level. The permissible suction height  $h_S$  results from the total pressure loss; it must not, however, be higher than  $h_{S \text{ max}} = 800 \text{ mm}$ .

The suction pressure at port **S** must also not fall below the minimum value of 0.8 bar absolute during operation (cold start 0.5 bar absolute).

When designing the reservoir, ensure that there is adequate distance between the suction line and the drain line. We recommend using a baffle (baffle plate) between suction line and drain line. A baffle improves the air separation ability as it gives the hydraulic fluid more time for desorption. Apart from that, this prevents the heated return flow from being drawn directly back into the suction line. The suction port must be supplied with air-free, calmed and cooled hydraulic fluid.

#### Installation position

See the following examples 1 to 12. Further installation positions are available upon request. Recommended installation position: 1 and 2.

#### **Notice**

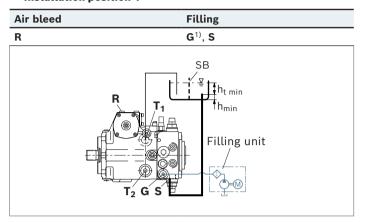
- ► Size 71 to 125 With the "drive shaft upwards" installation position, an **R**<sub>1</sub> port is necessary (special version).
- ▶ For optimum function and dynamics of the axial piston unit, a complete filling of the two stroking chambers X₁ and X₂ with hydraulic fluid is required. By swiveling the swashplate several times during commissioning, this can usually be be ensured. In case of unfavorable installation positions, air bleeding of the stroking chambers may take some time, so we recommend filling the stroking chambers via ports X₁ and X₂ before installation.
- ► In certain installation positions, an influence on the adjustment or control can be expected. Gravity, dead weight and case pressure can cause minor characteristic shifts and changes in response time.

Key	
R	Air bleed port
$\mathbf{R}_1$	Air bleed port (special version)
S	Suction port
G	Boost pressure port inlet
<b>T</b> <sub>1</sub> , <b>T</b> <sub>2</sub>	Drain port
SB	Baffle (baffle plate)
h <sub>t min</sub>	Minimum required immersion depth 7.87 in (200 mm)
h <sub>min</sub>	Minimum required distance to reservoir bottom 3.94 in (100 mm)
h <sub>S max</sub>	Maximum permissible suction height 31.5 in (800 mm)

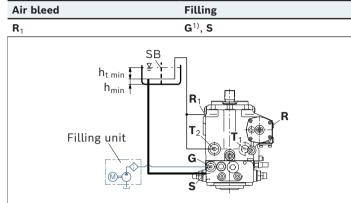
# Below-reservoir installation (standard)

Below-reservoir installation means that the axial piston unit is installed outside of the reservoir below the minimum fluid level of the reservoir.

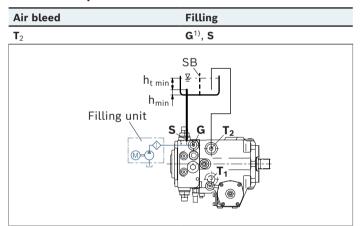
#### ▼ Installation position 1



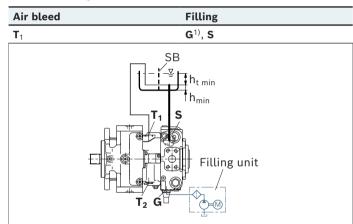
#### ▼ Installation position 4



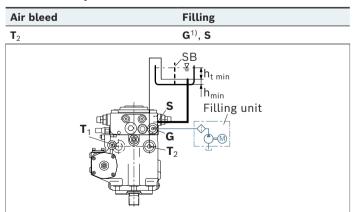
## ▼ Installation position 2



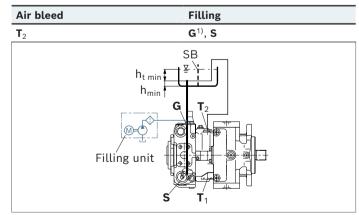
## ▼ Installation position 5



# ▼ Installation position 3



# ▼ Installation position 6



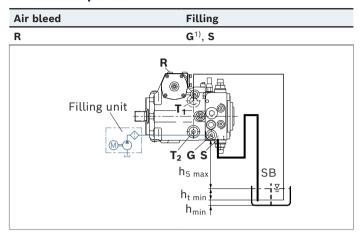
<sup>1)</sup> Recommendation: Filling with filling unit. When filling without filling unit, the pump must be filled at the highest drain port.

#### Above-reservoir installation

Above-reservoir installation means that the axial piston unit is installed above the minimum fluid level of the reservoir.

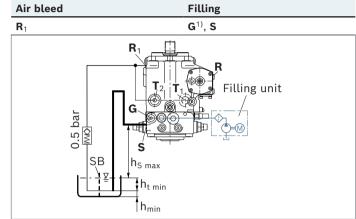
Observe the maximum permissible suction height  $h_{S max}$  = 31.50 in (800 mm).

#### ▼ Installation position 7

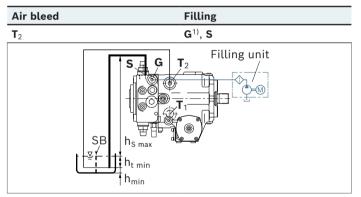


# Recommendation for installation position 10 (drive shaft upward): A check valve in the drain line (cracking pressure 7.5 psi (0.5 bar)) can prevent the housing area from draining.

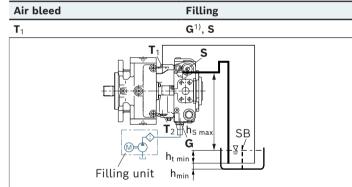
#### ▼ Installation position 10



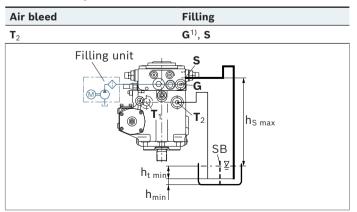
#### ▼ Installation position 8



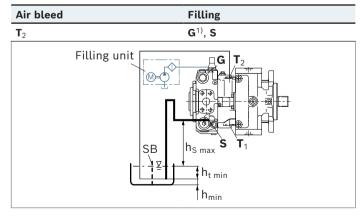
## ▼ Installation position 11



## ▼ Installation position 9



# ▼ Installation position 12



Recommendation: Filling with filling unit.
 When filling without filling unit, the pump must be filled at the highest drain port.

# **Project planning notes**

- ▶ The pump is designed to be used in a closed circuit.
- ► The project planning, installation and commissioning of the axial piston unit requires the involvement of skilled personnel.
- ▶ Before using the axial piston unit, please read the corresponding instruction manual completely and thoroughly. If necessary, this can be requested from Bosch Rexroth.
- ► Before finalizing your design, please request a binding installation drawing.
- ► The specified data and notes contained herein must be observed.
- ► Depending on the operating conditions of the axial piston unit (working pressure, fluid temperature), the characteristic curve may shift.
- ▶ Preservation: Our axial piston units are supplied as standard with preservation protection for a maximum of 12 months. If longer preservation protection is required (maximum 24 months), please specify this in plain text when placing your order. The preservation periods apply under optimal storage conditions, details of which can be found in the data sheet 90312 or the instruction manual.
- ► Not all versions of the product are approved for use in a safety function according to ISO 13849. Please consult the responsible contact person at Bosch Rexroth if you require reliability parameters (e.g. MTTF<sub>D</sub>) for functional safety.
- ▶ Depending on the type of control used, electromagnetic effects can be produced when using solenoids.

  Applying a direct voltage signal (DC) to solenoids does not create electromagnetic interference (EMI) nor is the solenoid affected by EMI. Electromagnetic interference (EMI) potential exists when operating and controlling a solenoid with a modulated direct voltage signal (e.g. PWM signal) Appropriate testing and measures should be taken by the machine manufacturer to ensure other components or operators (e.g. with pacemaker) are not affected by this potential.
- ▶ Pressure cut-off (hydraulic or electronic) is not a sufficient safeguard against pressure overload. Therefore, a pressure relief valve must be added to the hydraulic system (integrated in the pump or external in the system). Observe the technical limits of the pressure relief valves here.

- ▶ With dynamic power flow (change of pumps to operation as a motor) a maximum of 95%  $V_{\rm g\ max}$  is permissible. We recommend configuring the software accordingly.
- ▶ Please note that a hydraulic system is an oscillating system. This can lead, for example, to the stimulation the natural frequency within the hydraulic system during operation at constant rotational speed over a long period of time. The stimulator frequency of the pump is 9 times the rotational speed frequency. This can be prevented, for example, with suitably designed hydraulic lines.
- ► Please note the details regarding the tightening torques of port threads and other threaded joints in the instruction manual.
- ▶ The ports and fastening threads are designed for the  $p_{\text{max}}$  permissible pressures of the respective ports, see the connection tables. The machine or system manufacturer must ensure that the connecting elements and lines correspond to the specified application conditions (pressure, flow, hydraulic fluid, temperature) with the necessary safety factors.
- ► The service ports and function ports are only intended to accommodate hydraulic lines.

# **Safety instructions**

- ▶ During and shortly after operation, there is a risk of burns on the axial piston unit and especially on the solenoids. Take the appropriate safety measures (e.g. by wearing protective clothing).
- Moving parts in control equipment (e.g. valve spools) can, under certain circumstances, get stuck in position as a result of contamination (e.g. contaminated hydraulic fluid, abrasion, or residual dirt from components). As a result, the hydraulic fluid flow and the build-up of torque in the axial piston unit can no longer respond correctly to the operator's specifications. Even the use of various filter elements (external or internal flow filtration) will not rule out a fault but merely reduce the risk.
  - The machine/system manufacturer should test whether additional measures are required on the machine for the relevant application in order to bring the driven consumer into a safe position (e.g., safe stop) and make sure any measures are properly implemented.
- Moving parts in high-pressure relief valves may in certain circumstances become stuck in an undefined position due to contamination (e.g. impure hydraulic fluid). This can result in restriction or loss of loadholding functions in lifting winches.
  - The machine/system manufacturer must check whether additional measures are required on the machine for the relevant application in order to keep the load in a safe position and ensure they are properly implemented.

# **Bosch Rexroth AG**

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